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An Analytic Method for S -Expansion involving Resonance and Reduction

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*While I was sitting one night with a poet
friend watching a great opera performed in a
tent under arc lights, the poet took my arm
and pointed silently. Far up, blundering out
of the night, a huge Cecropia moth swept
past from light to light over the posturings of
the actors. "He doesn't know," my friend
whispered excitedly. "He's passing through
an alien universe brightly lit but invisible to
him. He's in another play; he doesn't see us.
He doesn't know. Maybe it's happening right
now to us."*

Loren Eiseley

Index

1. Summary	IV
1. Abstract	V
1. Introduction	1
2. Review of S-expansion, reduction, 0_S-reduction (and 0_S-resonant-reduction), and resonance	3
2.1 S-expansion of Lie (super)algebras.....	3
2.2 Reduced Lie (super)algebras.....	4
2.3 0-reduction (and 0-resonant-reduction) of S-expanded Lie (super)algebras.....	4
2.4 Resonant subalgebras for a semigroup.....	6
3. Theoretical construction of the analytic method for finding the semigroup(s)	7
3.1 Identification criterion.....	15
3.2 A note on associativity.....	22
4. Examples of application	23
4.1 From the Bianchi Type I algebra (BTI) to the Bianchi Type II one (BTII).....	23
4.2 $iso(2, 1)$ from the 0_S -resonant-reduction of $so(2, 2)$	28
4.3 The Maxwell algebra (M) as a 0_S -resonant-reduction of the Anti-de Sitter (AdS) Lie algebra.....	29
4.4 From the supersymmetric Lie algebra $osp(32/1)$ to the hidden superalgebra underlying D = 11 supergravity.....	31
5. Comments and possible developments	34
6. Conclusions	36
7. Acknowledgment	37
Appendix	
A. Detailed calculations for moving from the Bianchi Type I algebra (BTI) to the Bianchi Type II algebra (BTII).....	38
B. Detailed calculations for reaching $iso(2; 1)$, starting from $so(2; 2)$	42
C. Detailed calculations for moving from the Anti-de Sitter (AdS) algebra to the Maxwell algebra.....	46
D. Detailed calculations for reaching the hidden superalgebra underlying D = 11 supergravity, starting from the supersymmetric Lie algebra $osp(32/1)$	50
References	57

Summary

This thesis is based on the reconstruction of the S-expansion method [5] on an analytical way. This means to convert the method in an analytic one without random process or the needed to use computational algorithms to find a Lie (Super)algebra from another one, the key is the use of a general disjoint union of discrete and finite sets wick elements have in principle the closure property (Magma) and a very especial element (also been closed under the internal binary set operation) whose job is to abelianizate those commutation rules that are nedded to obtain the exact description of the wanted Lie (Super)Algebra. The steps to carry out along the use of this analytical method can be summarized as follows:

- 1) Get the required information from the starting and arrival Lie (Super)Algebras, this is; The total dimensionality and the subspace dimensionality of both in an equivalent algebraic partition (Splitting).
- 2) Put this data on the linear equation system that we have constructed wick give us just one exact solution in terms of a set of numbers that must belong to the atural numbers, if it's not the case (solution containing numbers belonging to other algebraic fields like rationals for example) the immediate answer is *the starting algebra and the arrival one are not connect by means of an S-expansion procedure*.
- 3) If the solution is *natural* we proceed to construct the commutation rules of the S-expanded structure. The very interesting thing is that the linear system of equations provide us also the cardinality of the unique set of the partition that must be multiplied whit its specific subspace (coming from the starting algebra). In this manner the new commutation rules (the S-expanded ones) contains the information about the way in which the original subspaces commutes among them and this information is traspassed to the way in which the several subsets of the partition must be multiplied using what we call the *composed index*. Untill this point we have used all the information that we need from the starting algebra. It's necessary to recall that in all the S-expanded commutation relationships is present the *zero element* taken axiomatically from the non analytical version of the method. This very important element is used in the next step.
- 4) Having to our disposition the S-expanded commutation rules we use what we call *The identification criterion*, this is a tool that take allow us to identify the S-expanded generators with generators of the arrival algebra using the fact that the S-expansion procedure doesn't produce changes in the internal structure of the generators as transformation operators, so a rotation, translation or supersymmetry transformation, among others in the arrival algebra must be costructed in base of a rotation, translation or supersymmetry transformation coming from the starting one. This finally allow us to discover wick commutators becomes abelianized by the selection of the zero element in the linear combination (right side) that defines the subspace where *falls* the commutators product of two generators.

With the step 3 we find the way in wick the different elemententering the partition are related under the internal binary multiplication of the closed set and with the step 4 are founded in detail the binary multiplication rule for each pair of set elements lying inside each element (subset) of the partition. In this way we have obtained the suitable set that bring us from the starting algebra to the required one, this set could be a semigroup or not depending on the implementation of *theorem 3*.

So now it's more simple to perform the S-expansion procedure in an analytical and elegant way.

Abstract

In this paper we describe an analytic method able to give the multiplication table(s) of the set(s) involved in an S-expansion process (with either resonance or 0-resonant-reduction) for reaching a target Lie (super)algebra from a starting one, after having properly chosen the partitions over subspaces of the considered (super)algebras.

This analytic method gives us a simple set of expressions to find the subset decomposition of the set(s) involved in the process. Then, we use the information coming from both the initial (super)algebra and the target one for reaching the multiplication table(s) of the mentioned set(s). We also give some interesting examples of application, which check and corroborate our analytic procedure and also generalize some result already presented in the literature.



1 Introduction

The relation of given Lie (super)algebras among themselves, and in particular the derivation of new (super)algebras from other ones, is a problem of great interest, in both Mathematics and Physics, since it involves the problem of mixing (super)algebras, which is a non-trivial way of enlarging spacetime symmetries.

One method to connect different (super)algebras is the *expansion* procedure, introduced for the first time in [1], and subsequently studied under different scenarios in [2–4]. In 2006, a natural outgrowth of the power series expansion method was proposed (see Ref.s [5–7]), which is based on combining the structure constants of the initial (super)algebra with the inner multiplication law of a discrete set S with the structure of a semigroup, in order to define the Lie bracket of a new S -expanded (super)algebra. From the physical point of view, several (super)gravity theories have been extensively studied using the S -expansion approach, enabling numerous results over recent years (see Ref.s [8–32]) in this context.

The S -*expansion* method replicates through the elements of a semigroup the structure of the original (super)algebra into a new one. The basis of the S -expansion consists, in fact, on combining the multiplication law of a semigroup S with the structure constants of a Lie (super)algebra \mathcal{G} [5]; The new Lie (super)algebra obtained through this procedure is called S -*expanded (super)algebra*, and it is written as $\mathcal{G}_S = S \otimes \mathcal{G}$.

There are two facets applicable in the S -expansion method, which offer great manipulation on (super)algebras, *i.e.* *resonance* and *reduction*. The role of *resonance* is that of transferring the structure of the semigroup to the target (super)algebra, and therefore to control its structure with a suitable choice on the semigroup partitions. Meanwhile, *reduction* plays a peculiar role in cutting the (super)algebra properly, thanks to the existence of a zero element in the set involved in the procedure, which allows, for example, the Inönü-Wigner contraction (see Ref.s [33, 34]).

A fundamental task to accomplish in the S -expansion is to find the appropriate semigroup connecting two different (super)algebras, but this task involves a non-trivial process, due to the fact that until today there is no analytic procedure to unequivocally derive the semigroup performing the required expansion.

With this in mind, in the present work we describe an *analytic method* to find the correct semigroup(s) allowing S -expansion (involving either resonance or 0_S -resonant-reduction) between two different (super)algebras, once the partitions over subspaces have been properly chosen.

This work is organized as follows: In Section 2, we give a review of S -expansion, reduction, 0_S -reduction (and 0_S -resonant-reduction), and resonance. In Section 3, we develop an analytic procedure to obtain the semigroup(s) multiplication table(s) linking different Lie (super)algebras. Then, examples of application are presented in Section 4. Section 5 contains a summary of our results, with comments and possible developments. In the Appendix, we give the detailed calculations for reaching the results we have obtained.

We finish the present work with a conclusion, in which it's emphasize the technical part of the analytical method. Also it's given a deep analisys that bring us beyond the detailed calculations and focalize in the *hierarchy that exist between the principal postulates and foundations concepts in the formulation of the S-expansion*, for example the stablishment that the need of certain porportionality between the starting and arrival algebras has te consequence that the partition of the magma (at least) must have a resonant behavior with respect to the way in wich the several subspaces in the starting algebra closed under commutation.



2 Review of S -expansion, reduction, 0_S -reduction (and 0_S -resonant-reduction), and resonance

The expansion of a Lie (super)algebra entails finding a new (super)algebra starting from an original one. The so called S -*expansion*, that is an incarnation of the *expansion method* described in [2], involves a finite abelian semigroup S to accomplish this task, and it has the feature of being very simple and direct (see Ref. [5]). The S -expansion method allows to obtain new Lie (super)algebras starting from an original one by choosing an abelian semigroup leading to *resonant*, *reduced* or *resonant-reduced* subalgebras.

2.1 S -expansion of Lie (super)algebras

The S -expansion procedure consists in combining the structure constants of a Lie (super)algebra \mathcal{G} with the inner multiplication law of a semigroup S , to define the Lie bracket of a new, S -expanded (super)algebra $\mathcal{G}_S = S \otimes \mathcal{G}$.

Let $S = \{\lambda_\alpha\}$, with $\alpha = 1, \dots, N$, be a finite, abelian semigroup with *two-selector* $K_{\alpha\beta}^\gamma$ defined by

$$K_{\alpha\beta}^\gamma = \begin{cases} 1, & \text{when } \lambda_\alpha \lambda_\beta = \lambda_\gamma, \\ 0, & \text{otherwise.} \end{cases} \quad (2.1)$$

Let \mathcal{G} be a Lie (super)algebra with basis $\{T_A\}$ and structure constants C_{AB}^C , defined by the commutation relations

$$[T_A, T_B] = C_{AB}^C T_C. \quad (2.2)$$

Denote a basis element of the direct product $S \otimes \mathcal{G}$ by $T_{(A,\alpha)} = \lambda_\alpha T_A$ and consider the induced commutator

$$[T_{(A,\alpha)}, T_{(B,\beta)}] \equiv \lambda_\alpha \lambda_\beta [T_A, T_B]. \quad (2.3)$$

Then one can show (see Ref. [5]) that the product

$$\mathcal{G}_S = S \otimes \mathcal{G} \quad (2.4)$$

corresponds to the Lie (super)algebra given by

$$[T_{(A,\alpha)}, T_{(B,\beta)}] = K_{\alpha\beta}^\gamma C_{AB}^C T_{(C,\gamma)}, \quad (2.5)$$

whose structure constants can be written as

$$C_{(A,\alpha)(B,\beta)}^{(C,\gamma)} = K_{\alpha\beta}^\gamma C_{AB}^C. \quad (2.6)$$

The product $[\cdot, \cdot]$ defined in (2.5) is also a Lie product, since it is linear, antisymmetric and it satisfies the Jacobi identity. This product defines a new Lie (super)algebra characterized by $(\mathcal{G}_S, [\cdot, \cdot])$, which is called *S -expanded Lie (super)algebra*. This implies that, for every abelian semigroup S and Lie (super)algebra \mathcal{G} , the (super)algebra \mathcal{G}_S obtained through the product (2.4) is also a Lie (super)algebra, with a Lie bracket given by (2.5) ¹.

¹However, as we will show in the present work, there exist some exception in which, in order to reach

2.2 Reduced Lie (super)algebras

In [5], the authors gave a definition in order to introduce the concept of *reduction* of Lie (super)algebras. It essentially reads as follow: Let us consider a Lie (super)algebra \mathcal{G} of the form $\mathcal{G} = V_0 \oplus V_1$, where V_0 and V_1 are two subspaces respectively given by $V_0 = \{T_{a_0}\}$ and $V_1 = \{T_{a_1}\}$. When $[V_0, V_1] \subset V_1$, that is to say when the commutation relations between generator present the following form

$$[T_{a_0}, T_{b_0}] = C_{a_0 b_0}^{c_0} T_{c_0} + C_{a_0 b_0}^{c_1} T_{c_1}, \quad (2.7)$$

$$[T_{a_0}, T_{b_1}] = C_{a_0 b_1}^{c_1} T_{c_1}, \quad (2.8)$$

$$[T_{a_1}, T_{b_1}] = C_{a_1 b_1}^{c_0} T_{c_0} + C_{a_1 b_1}^{c_1} T_{c_1}, \quad (2.9)$$

one can show that the structure constants $C_{a_0 b_0}^{c_0}$ satisfy the Jacobi identity themselves, and therefore

$$[T_{a_0}, T_{b_0}] = C_{a_0 b_0}^{c_0} T_{c_0} \quad (2.10)$$

itself corresponds to a Lie (super)algebra, which is called *reduced* (super)algebra of \mathcal{G} .

In spite of the similarity of the concepts, a reduced algebra does *not*, in general, correspond to a subalgebra (see Ref. [5]).

2.3 0_S -reduction (and 0_S -resonant-reduction) of S -expanded Lie (super)algebras

The concept of *reduction* of Lie (super)algebras, and in particular 0_S -*reduction*, was introduced in [5]. It involves the extraction of a smaller (super)algebra from a given Lie (super)algebra \mathcal{G}_S , when certain conditions are met.

Now, in order to give a review of 0_S -*reduction*, let us consider an abelian semigroup S and the S -expanded (super)algebra $\mathcal{G}_S = S \otimes \mathcal{G}$. When the semigroup S has a *zero element* $0_S \in S$ (in the following, we will adopt the notation $0_S \equiv \lambda_{0_S}$, in order to make clearer the multiplication rules of the semigroup(s) involved in the process), this element plays a peculiar role in the S -expanded (super)algebra, as it was shown in [5]. In fact, we can split the semigroup S into non-zero elements λ_i , $i = 0, \dots, N$, and a zero element $\lambda_{N+1} = 0_S = \lambda_{0_S}$. The zero element λ_{0_S} is defined as one for which

$$\lambda_{0_S} \lambda_\alpha = \lambda_\alpha \lambda_{0_S} = \lambda_{0_S}, \quad (2.11)$$

for each $\lambda_\alpha \in S$. Under this assumption, we can write $S = \{\lambda_i\} \cup \{\lambda_{N+1} = \lambda_{0_S}\}$, with $i = 1, \dots, N$ (here and in the following, the Latin index run only on the non-zero elements of

a target Lie (super)algebra, is not always necessary to use a semigroup, but just an abelian set, since the procedure can be performed without requiring associativity. This is due to the fact that, in that cases, the Jacobi identity is trivially satisfied (each term of the Jacobi identity is equal to zero).

the semigroup \tilde{S}). Then, the two-selector satisfies the relations

$$K_{i,N+1}^j = K_{N+1,i}^j = 0, \quad (2.12)$$

$$K_{i,N+1}^{N+1} = K_{N+1,i}^{N+1} = 1, \quad (2.13)$$

$$K_{N+1,N+1}^j = 0, \quad (2.14)$$

$$K_{N+1,N+1}^{N+1} = 1, \quad (2.15)$$

which mean, when translated into multiplication rules,

$$\lambda_{N+1}\lambda_i = \lambda_{N+1}, \quad (2.16)$$

$$\lambda_{N+1}\lambda_{N+1} = \lambda_{N+1}. \quad (2.17)$$

Therefore, for $\mathcal{G}_S = S \otimes \mathcal{G}$ we can write the commutation relations

$$[T_{(A,i)}, T_{(B,j)}] = K_{ij}^k C_{AB}^C T_{(C,k)} + K_{ij}^{N+1} C_{AB}^C T_{(C,N+1)}, \quad (2.18)$$

$$[T_{(A,N+1)}, T_{(B,j)}] = C_{AB}^C T_{(C,N+1)}, \quad (2.19)$$

$$[T_{(A,N+1)}, T_{(B,N+1)}] = C_{AB}^C T_{(C,N+1)}. \quad (2.20)$$

If we now compare these commutation relations with (2.7), (2.8), and (2.9), we clearly see that

$$[T_{(A,i)}, T_{(B,j)}] = K_{ij}^k C_{AB}^C T_{(C,k)} \quad (2.21)$$

are the commutation relations of a *reduced* Lie (super)algebra generated by $\{T_{(A,i)}\}$, whose structure constants are $K_{ij}^k C_{AB}^C$.

The reduction procedure, in this particular case, is equivalent to the imposition of the condition

$$T_{A,N+1} = \lambda_{0_S} T_A = 0. \quad (2.22)$$

We can notice that, in this case, the reduction abelianizes large sectors of the (super)algebra, and that for each j satisfying $K_{ij}^{N+1} = 1$ (that is to say $\lambda_{0_S}\lambda_j = \lambda_{N+1}$), we have

$$[T_{(A,i)}, T_{(B,j)}] = 0. \quad (2.23)$$

The above considerations led the authors of [5] to a definition which essentially reads: Let S be an abelian semigroup with a zero element $\lambda_{0_S} \in S$, and let $\mathcal{G}_S = S \otimes \mathcal{G}$ be an S -expanded (super)algebra. Then, the (super)algebra obtained by imposing the condition

$$\lambda_{0_S} T_A = 0 \quad (2.24)$$

on \mathcal{G}_S (or on a subalgebra of it) is called 0_S -*reduced (super)algebra* of \mathcal{G}_S (or of the subalgebra).

When the 0_S -reduced (super)algebra \mathcal{G}_{S_R} presents a structure which is *resonant* with respect to the structure of the semigroup involved in the S -expansion process, the procedure takes the name of 0_S -*resonant-reduction*.

2.4 Resonant subalgebras for a semigroup

As we have seen, the S -expanded (super)algebra has a fairly simple structure. Furthermore, with the reduction procedure we can arrive to a more interesting (super)algebra, where it is possible to demand some abelian commutators.

Additionally, there is another way to get smaller (super)algebras from $S \otimes \mathcal{G}$, which strongly depends on the structure of semigroup, that we shall see below.

Let $\mathcal{G} = \bigoplus_{p \in I} V_p$ be a decomposition of \mathcal{G} in subspaces V_p , where I is a set of indices. For each $p, q \in I$ it is always possible to define the subsets $i_{(p,q)} \subset I$, such that

$$[V_p, V_q] \subset \bigoplus_{r \in i_{(p,q)}} V_r, \quad (2.25)$$

where the subsets $i_{(p,q)}$ store the information on the subspace structure of \mathcal{G} .

Now, let $S = \bigcup_{p \in I} S_p$ be a subset decomposition of the abelian semigroup S , such that

$$S_p \cdot S_q \subset \bigcup_{r \in i_{(p,q)}} S_r, \quad (2.26)$$

where the product $S_p \cdot S_q$ is defined as

$$S_p \cdot S_q = \{\lambda_\gamma \mid \lambda_\gamma = \lambda_{\alpha_p} \lambda_{\alpha_q}, \text{ with } \lambda_{\alpha_p} \in S_p, \lambda_{\alpha_q} \in S_q\} \subset S. \quad (2.27)$$

When such subset decomposition $S = \bigcup_{p \in I} S_p$ exists, then we say that this decomposition is in *resonance* with the subspace decomposition of \mathcal{G} , $\mathcal{G} = \bigoplus_{p \in I} V_p$.

The resonant subset decomposition is crucial in order to systematically extract subalgebras from the S -expanded (super)algebra $\mathcal{G}_S = S \otimes \mathcal{G}$, as it was enunciated and proven with the following theorem in Ref. [5]²:

Theorem 1. *Let $\mathcal{G} = \bigcup_{p \in I} V_p$ be a subspace decomposition of \mathcal{G} , with a structure described by equation (2.25), and let $S = \bigcup_{p \in I} S_p$ be a resonant subset decomposition of the abelian semigroup S , with the structure given in equation (2.26). Define the subspaces of $\mathcal{G}_S = S \otimes \mathcal{G}$ as*

$$W_p = S_p \otimes V_p, \quad p \in I. \quad (2.28)$$

Then,

$$\mathcal{G}_R = \bigoplus_{p \in I} W_p \quad (2.29)$$

is a subalgebra of $\mathcal{G}_S = S \otimes \mathcal{G}$, called *resonant subalgebra* of \mathcal{G}_S .

The proof of Theorem 1 can be found in Ref. [5].

²This theorem corresponds to ‘‘Theorem IV.2’’ given in Ref. [5].

3 Theoretical construction of the analytic method for finding the semigroup(s)

In this section, we develop an *analytic method* to find the semigroup(s) involved in the S -expansion procedure (with either resonance or 0_S -resonance-reduction) for moving from an initial Lie (super)algebra to a target one, once the partitions over subspaces of the considered (super)algebras have been properly chosen.

To this aim, let us consider a finite Lie (super)algebra \mathcal{G} , which can be decomposed into N subspaces V_A , with $A = 0, 1, \dots, N - 1$, and can be written as their direct sum, namely $\mathcal{G} = \bigoplus_A V_A$. Then, let us consider a target Lie (super)algebra \mathcal{G}_{SRR} (where the label “ S_{RR} ” stands for “ S -expanded, (0_S -)resonant-reduced”), which can analogously be decomposed into N subspaces \tilde{V}_A , with $A = 0, 1, \dots, N - 1$, and can be written as their direct sum, namely $\mathcal{G}_{SRR} = \bigoplus_A \tilde{V}_A$ ³.

Let us also consider an abelian, discrete and finite set S , with P elements, including the zero element λ_0 , which can be decomposed into N subsets S_A , $A = 0, 1, \dots, N - 1$.

We will denote each of this subsets with S_{Δ_A} , where the composed index Δ_A expresses both the cardinality (number of elements) of each subsets (capital Greek index, Δ), and the subspace associated (capital Latin index, A, B, C, \dots). The association between the subsets and the (super)algebra subspaces is unique (under the *resonance* condition), and we will see that for each value of A we will have a unique value for the corresponding index Δ . This is the reason why we are using this composite index.

Thus, let us consider the decomposition of the set \tilde{S} in terms of its subsets partition

$$\tilde{S} = \sqcup_{\Delta_A} S_{\Delta_A}, \quad (3.1)$$

where with the symbol \sqcup we mean the disjoint union of sets.

We can now use this general partition and perform a 0_S -resonant-reduced process⁴, linking the original Lie (super)algebra \mathcal{G} and the target one \mathcal{G}_{SRR} . In this way, we get

$$\begin{aligned} \mathcal{G}_{SRR} &= \tilde{V}_0 \oplus \tilde{V}_1 \oplus \dots \oplus \tilde{V}_{N-1} = \\ &= (S_{\Delta_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0) \oplus \\ &\quad \oplus (S_{\Delta_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1) \oplus \\ &\quad \oplus \dots \oplus (S_{\Delta_{N-1}} \otimes V_{N-1}) \oplus (\{\lambda_{0_S}\} \otimes V_{N-1}), \end{aligned} \quad (3.2)$$

³Here and in the following, the quantities with a “tilde” symbol above will refer to quantities of the target (super)algebra.

⁴A process which involves only resonance would be a simpler one, and it will be briefly treated in the following.

Since we can factorize the zero element, the above relation can be simply rewritten as

$$\begin{aligned}
\mathcal{G}_{SRR} &= \tilde{V}_0 \oplus \tilde{V}_1 \oplus \cdots \oplus \tilde{V}_{N-1} = \\
&= [(S_{\Delta_0} \otimes V_0) \oplus (S_{\Delta_1} \otimes V_1) \oplus \cdots \oplus (S_{\Delta_{N-1}} \otimes V_{N-1})] \oplus (\{\lambda_{0_S}\} \otimes \mathcal{G}).
\end{aligned} \tag{3.3}$$

As we have said above, equation (3.3) comes from the study of a 0_S -resonant-reduced process, which we can be written in a more formal way as

$$\begin{aligned}
\mathcal{G}_{red-res} &= \{ \sqcup_{\Delta_A} \{S_{\Delta_A}\} \otimes V_0 - (\sqcup_{\Delta_A \neq 0} \{S_{\Delta_A}\} \otimes V_0 + 0_s V_0) \} \oplus \dots \\
&\oplus \{ \sqcup_{\Delta_A \neq 1} \{S_{\Delta_A}\} \otimes V_1 - (\sqcup_{\Delta \neq \Lambda_1} \{S_{\Delta}\} \otimes V_1 + 0_s V_1) \} \\
&\oplus \dots \oplus \{ \sqcup_{\Delta_A} \{S_{\Delta_A}\} \otimes V_{N-1} - (\sqcup_{\Delta_A \neq N-1} \{S_{\Delta_A}\} \otimes V_{N-1} + 0_s V_{N-1}) \} \\
&= \{ \sqcup_{\Delta} \{S_{\Delta}\} - (\sqcup_{\Delta \neq \Lambda_0} \{S_{\Delta}\} + 0_s) \} \otimes V_0 \\
&\oplus \{ \sqcup_{\Delta} \{S_{\Delta}\} - (\sqcup_{\Delta \neq \Lambda_1}^N \{S_{\Delta}\} + 0_s) \} \otimes V_1 \\
&\oplus \{ \sqcup_{\Delta} \{S_{\Delta}\} - (\sqcup_{\Delta \neq \Lambda_{N-1}} \{S_{\Delta}\} + 0_s) \} \otimes V_{N-1} \\
&= \{ \tilde{S} \ominus (\sqcup_{\Delta_A \neq 0} \{S_{\Delta_A}\} + 0_s) \} \otimes V_0 \\
&\oplus \{ \tilde{S} \ominus (\sqcup_{\Delta_A \neq 1} \{S_{\Delta_A}\} + 0_s) \} \otimes V_1 \\
&\oplus \dots \oplus \{ \tilde{S} \ominus (\sqcup_{\Delta_A \neq N-1} \{S_{\Delta_A}\} + 0_s) \} \otimes V_{N-1} \\
&= \bigoplus_{T=0}^{N-1} \left[\tilde{S} \ominus (\sqcup_{\Delta_A \neq T} S_{\Delta_A} \oplus \lambda_{0_S}) \right] \otimes V_T,
\end{aligned}$$

where we have denoted with \oplus and \ominus the direct sum and subtraction over subsets, respectively.

From expression (??), taking into account the dimensions of the subspaces involved in the partitions of the considered (super)algebras, the following system of equations arises:

$$\left\{ \begin{array}{l} \dim(\tilde{V}_0) = \dim(V_0) \left(\tilde{P} - 1 - \sum_{A \neq 0}^{N-1} \Delta_A \right), \\ \dim(\tilde{V}_1) = \dim(V_1) \left(\tilde{P} - 1 - \sum_{A \neq 1}^{N-1} \Delta_A \right), \\ \vdots \\ \dim(\tilde{V}_{N-1}) = \dim(V_{N-1}) \left(\tilde{P} - 1 - \sum_{A \neq N-1}^{N-1} \Delta_A \right), \\ \tilde{P} = \sum_A^{N-1} \Delta_A + 1, \end{array} \right. \quad (3.4)$$

where in the expression $\tilde{P} = \sum_A^{N-1} \Delta_A + 1$ we have $\tilde{P} \geq P$ (let us remember that P is the total number of elements of the set \tilde{S}), and the $+1$ contribution is given by the presence of the zero element λ_{0_S} .

We can rewrite the system above in the following simpler form (which comes directly from relation (3.3)):

$$\left\{ \begin{array}{l} \dim(\tilde{V}_0) = \dim(V_0) (\Delta_0), \\ \dim(\tilde{V}_1) = \dim(V_1) (\Delta_1), \\ \vdots \\ \dim(\tilde{V}_{N-1}) = \dim(V_{N-1}) (\Delta_{N-1}), \\ \tilde{P} = \sum_A^{N-1} \Delta_A + 1. \end{array} \right. \quad (3.5)$$

If this system admits a solution (which, if exists, is *unique*), then we will immediately know, for construction, that it is possible to reach a S -expanded, 0_S -resonant-reduced (super)algebra $\mathcal{G}_{S_{RR}}$ starting from the initial Lie (super)algebra \mathcal{G} with the considered partition over subspaces, and we will also know the way in which the elements of \tilde{S} are distributed into different subsets, *i.e.* the cardinality of the subsets associated with the subspaces of the initial Lie (super)algebra.

In fact, knowing the dimensions of the partitions of both the initial and the target (super)algebra, the system (3.5) can be solved with respect to the variables

$$\tilde{P}, \Delta_A, A = 0, \dots, N-1, \quad (3.6)$$

and the solution (3.6) admits only values in \mathbb{N}^* (the value zero is obviously excluded).

We can observe that the system (3.5) admits solution if and only if the dimensions of the subspaces of the target (super)algebra are proportional (multiples) to the dimensions of the respective subspaces of the initial one ⁵. Furthermore, this system admits solutions only if the number of subspaces in the partition of the target (super)algebra is equal to the number of subspaces in the partition of the starting one. These considerations offer a criterion to properly choose a partition over subspaces for both the initial and the target Lie (super)algebras, namely:

- The number of subspaces in the partition of the target (super)algebra must be equal to that of the starting (super)algebra;
- The dimensions of the subspaces of the target (super)algebra must be multiples of the dimensions of the respective subspaces of the initial one.

Once these two conditions over the partitions are met, one is able to develop our analytic method and find all the semigroup(s), *with respect to the chosen partitions*, linking the considered (super)algebras.

We can also observe that the system (3.5) can also be solved when considering an S -expansion including just a *resonant* processes, since it also contains the subsystem

$$\left\{ \begin{array}{l} \dim(\tilde{V}_0) = \dim(V_0)(\Delta_0), \\ \dim(\tilde{V}_1) = \dim(V_1)(\Delta_1), \\ \vdots \\ \dim(\tilde{V}_{N-1}) = \dim(V_{N-1})(\Delta_{N-1}), \\ \tilde{P} = \sum_A^{N-1} \Delta_A, \end{array} \right. \quad (3.7)$$

in which we can clearly see that we are now considering the variable $\tilde{P} = \sum_A^{N-1} \Delta_A$ *without* the +1 contribution, whose presence was due to the inclusion of the zero element λ_{0_S} . In this case, the solution to the system (3.7) is *unique* again, and the considerations done for the 0_S -resonant-reduced case still hold.

At this point, we know the cardinality of each of the subsets of the set \tilde{S} involved in the process. Now we can understand something more about the multiplication rules of the set \tilde{S} , by studying the adjoint representation of the initial Lie (super)algebra with respect to the partition over subspaces.

Thus, we construct, for each subspace, the adjoint representation with respect to the subspaces. This construction is based on the association

$$[V_A, V_B] \subset V_C \quad \longrightarrow \quad (C)_{AB}^C, \quad (3.8)$$

⁵This is the reason why, if the system (3.5) admits a solution, this solution is trivially unique.

where the index A, B, C can take the values $0, \dots, N-1$, and where the matrix $(C)_{AB}^C$ give us the adjoint representation over the subspace A , which can be written as

$$(C)_{AB}^C = \begin{pmatrix} (C)_{A0}^0 & (C)_{A0}^1 & \cdots & (C)_{A0}^{N-1} \\ (C)_{A1}^0 & (C)_{A1}^1 & \cdots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ (C)_{A N-1}^0 & \cdots & \cdots & (C)_{A N-1}^{N-1} \end{pmatrix}. \quad (3.9)$$

In this way, the matrix $(C)_{AB}^C$ is written by exploiting the commutation rules between the different partitions over the subspaces of the initial (super)algebra, and it contains the whole information about these partitions.

- The S -expanded adjoint representation in detail will acquire the following form:

$$(K_{(\alpha\Delta_A)})_{(\beta\Lambda_B)}^{(\gamma\Gamma_C)} (C_A)_B^C = \begin{pmatrix} (K_{(\alpha\Delta_A)})_{(\beta\Lambda_0)}^{(\gamma\Gamma_0)} (C_A)_0^0 & \cdots & \cdots & (K_{(\alpha\Delta_A)})_{(\beta\Lambda_0)}^{(\gamma\Gamma_R)} (C_A)_0^R \\ (K_{(\alpha\Delta_A)})_{(\beta\Lambda_1)}^{(\gamma\Gamma_0)} (C_A)_1^0 & \cdots & \cdots & (K_{(\alpha\Delta_A)})_{(\beta\Lambda_1)}^{(\gamma\Gamma_R)} (C_A)_1^R \\ \vdots & \cdots & \cdots & \vdots \\ (K_{(\alpha\Delta_A)})_{(\beta\Lambda_R)}^{(\gamma\Gamma_0)} (C_A)_R^0 & \cdots & \cdots & (K_{(\alpha\Delta_A)})_{(\beta\Lambda_R)}^{(\gamma\Gamma_R)} (C_A)_R^R \end{pmatrix}. \quad (3.10)$$

In particular:

$$\begin{aligned} (K_{(\alpha\Delta_A)})_{(\beta\Lambda_0)}^{(\gamma\Gamma_0)} (C_A)_0^0 &= \left(\left(\left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_n^l \right)_A \right)_0 \right)^0 \\ &= \begin{pmatrix} \left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_0^0 \right) & \cdots & \cdots & \left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_{\dim(V_0)}^{\dim(V_0)} \right) \\ \left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_1^0 \right) & \cdots & \cdots & \left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_1^{\dim(V_0)} \right) \\ \vdots & \cdots & \cdots & \vdots \\ \left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_{\dim(V_0)}^0 \right) & \cdots & \cdots & \left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_{\dim(V_0)}^{\dim(V_0)} \right) \end{pmatrix}_{A0}^0 \end{aligned}$$

so as we can see this has the structure

$$\left(\left(\left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} (C_m)_n^l \right)_A \right)_0 \right)^0 = \left(\left(\left((K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} \right) \otimes (C_m)_n^l \right)_A \right)_0^0 \quad (3.11)$$

and where⁶

⁶The index $\#\Delta_A$ represent the cardinality of the subset Δ_A .

$$(K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} = \begin{pmatrix} (K_{(0\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} & \cdots & \cdots & (K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{(\#\Gamma_0)\Gamma_0} \\ (K_{(1\Delta_A)})_{\beta\Lambda_0}^{\gamma\Gamma_0} & \ddots & & (K_{(\alpha\Delta_A)})_{\beta\Lambda_0}^{(\#\Gamma_0)\Gamma_0} \\ \vdots & & \ddots & \vdots \\ (K_{((\#\Delta_A)\Delta_A)})_{(\#\Lambda_0)\Lambda_0}^{\gamma\Gamma_0} & \cdots & \cdots & (K_{((\#\Delta_A)\Delta_A)})_{(\#\Lambda_0)\Lambda_0}^{(\#\Gamma_0)\Gamma_0} \end{pmatrix} \quad (3.12)$$

so we have show here the interesting structure of the remain representation for the S -expanded Lie algebra

$$(K_{(\alpha\Delta_A)})_{\beta\Lambda_B}^{\gamma\Gamma_C} \xrightarrow[\otimes]{} (C_m)_n^l \xrightarrow[\otimes]{} C_{AB}^C \quad (3.13)$$

For the case of low dimension Lie algebras we propose the following procedure that puts into practice part of the theoretical machinery exposed previously. This is because the adjoint representation for this cases is not too enormous and is handy to write it and recognize the correspondingly separation between the S -expanded subspaces. After this we are going to make use of the full theoretical construction for the supersymmetry case in which we'll note the true scope by using it.

From this adjoint-like representation over the subspaces of the initial (super)algebra, we can now write, according to the usual S -expansion procedure (as it was done in [5]), the relations

$$\begin{aligned} & [(S_{\Delta_A} \otimes V_A) \oplus (\{\lambda_{0_S}\} \otimes V_A), (S_{\Delta_B} \otimes V_B) \oplus (\{\lambda_{0_S}\} \otimes V_B)] = \\ & = \left(K_{(\Delta_A)(\Delta_B)}^{(\Delta_C)} (C)_{AB}^C \right) [(S_{\Delta_C} \otimes V_C) \oplus (\{\lambda_{0_S}\} \otimes V_C)], \end{aligned} \quad (3.14)$$

where we have also taken into account the presence of the zero element in the set \tilde{S} , since we have considered a 0_S -resonant-reduction process⁷. Here, the composite index Δ_A , Δ_B , and Δ_C label, as said before, the cardinality of the different subsets (labeled with the capital Greek index Δ), uniquely associated with the different subspace partitions (labeled with capital Latin index). In order to write the relation (3.14), we are also taking into account the following theorem:

Theorem 2. *In the S -expansion procedure, when the commutator of two generators in the original Lie (super)algebra falls into a linear combination involving more than one generator, all the terms appearing in this resultant linear combination of generators must share the same element of the set \tilde{S} involved in the procedure.*

Proof. The demonstration of this theorem can be treated as a proof by contradiction (*reductio ad absurdum*). In fact, if the linear combination of generators were coupled with different

⁷A process involving only resonance would be a simpler one, and it would require a similar (but simpler) analysis, since, in that case, one would relax the reduction condition.

elements of the set \tilde{S} involved in the procedure, we would have

$$\begin{aligned}
[T_{(A,\alpha)}, T_{(B,\beta)}] &= [\lambda_\alpha T_A, \lambda_\beta T_B] = \lambda_\alpha \lambda_\beta [T_A, T_B] = \\
&= K_{\alpha\beta}^{\gamma_1} C_{AB}^{C_1} T_{(C_1, \gamma_1)} + K_{\alpha\beta}^{\gamma_2} C_{AB}^{C_2} T_{(C_2, \gamma_2)} + \cdots + K_{\alpha\beta}^{\gamma_n} C_{AB}^{C_n} T_{(C_n, \gamma_n)} = \\
&= K_{\alpha\beta}^{\gamma_1} C_{AB}^{C_1} \lambda_{\gamma_1} T_{C_1} + K_{\alpha\beta}^{\gamma_2} C_{AB}^{C_2} \lambda_{\gamma_2} T_{C_2} + \cdots + K_{\alpha\beta}^{\gamma_n} C_{AB}^{C_n} \lambda_{\gamma_n} T_{C_n},
\end{aligned} \tag{3.15}$$

where $\{\lambda_\alpha, \lambda_\beta, \lambda_{\gamma_1}, \lambda_{\gamma_2}, \dots, \lambda_{\gamma_n}\} \in \tilde{S}$, $\{T_A\} \in V_A$, $\{T_B\} \in V_B$, $\{T_{C_1}, T_{C_2}, \dots, T_{C_n}\} \in V_C$ ⁸, and where

$$K_{\alpha\beta}^{\gamma_1} \neq K_{\alpha\beta}^{\gamma_2} \neq \cdots \neq K_{\alpha\beta}^{\gamma_n}. \tag{3.16}$$

Equations (3.15) and (3.16) would mean that different two-selectors were associated with the same resulting element, and, according to the definition of two-selector given in (2.1), this would imply

$$\lambda_\alpha \lambda_\beta = \lambda_{\gamma_1} = \lambda_{\gamma_2} = \lambda_{\gamma_n}, \tag{3.17}$$

with $\gamma_1 \neq \gamma_2 \neq \cdots \neq \gamma_n$, which would break the uniqueness of the internal composition law of the set \tilde{S} .

But this cannot be true, since the composition law associates each couple of elements λ_α and λ_β with a *unique* element λ_γ (as we can see in the definition (2.1)). Thus, we can conclude that when the commutator of two generators in the original Lie (super)algebra falls into a linear combination involving more than one generator, the terms appearing in this resultant linear combination of generators must be multiplied by the same element. \square

Theorem 2 reflects on the commutators involving the subspaces of the partition of the original Lie (super)algebra and the subsets of the set \tilde{S} .

In fact, if the subspaces involving the linear combination of generators were coupled with different elements of \tilde{S} , we would have

$$\begin{aligned}
& [(\{\lambda_{\alpha, \Delta_A}\} \otimes V_A) \oplus (\{\lambda_{0_S}\} \otimes V_A), (\{\lambda_{\beta, \Delta_B}\} \otimes V_B) \oplus (\{\lambda_{0_S}\} \otimes V_B)] = \\
& = \left(K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma_1, \Delta_C)} (C)_{AB}^C \right) [(\{\lambda_{\gamma_1, \Delta_C}\} \otimes V_C) \oplus (\{\lambda_{0_S}\} \otimes V_C)] + \\
& + \left(K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma_2, \Delta_C)} (C)_{AB}^C \right) [(\{\lambda_{\gamma_2, \Delta_C}\} \otimes V_C) \oplus (\{\lambda_{0_S}\} \otimes V_C)] + \\
& \quad \vdots \\
& + \left(K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma_n, \Delta_C)} (C)_{AB}^C \right) [(\{\lambda_{\gamma_n, \Delta_C}\} \otimes V_C) \oplus (\{\lambda_{0_S}\} \otimes V_C)],
\end{aligned} \tag{3.18}$$

where with $\lambda_{\alpha, \Delta_A}$ we denote an arbitrary element λ_α contained in the subset S_A , associated with the subspace V_A , with cardinality Δ ⁹, and where

$$K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma_1, \Delta_C)} \neq K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma_2, \Delta_C)} \neq \cdots \neq K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma_n, \Delta_C)}. \tag{3.19}$$

Equations (3.18) and (3.19) would mean that different two-selectors were associated with the same resulting element, which would break the uniqueness of the internal composition

⁸Here we denote with V_A , V_B , and V_C the subspaces of the partition over the original Lie (super)algebra.

⁹The same notation has been adopted in equation (3.18) for all the other elements of the set \tilde{S} .

law of the set \tilde{S} . Thus, since the composition law associates each couple of elements in \tilde{S} with a *unique* element of the set \tilde{S} , we can finally say that

$$\begin{aligned} & [(\{\lambda_{\alpha, \Delta_A}\} \otimes V_A) \oplus (\{\lambda_{0_S}\} \otimes V_A), (\{\lambda_{\beta, \Delta_B}\} \otimes V_B) \oplus (\{\lambda_{0_S}\} \otimes V_B)] = \\ & = \left(K_{(\alpha, \Delta_A)(\beta, \Delta_B)}^{(\gamma, \Delta_C)}(C)_{AB}^C \right) [(\{\lambda_{\gamma, \Delta_C}\} \otimes V_C) \oplus (\{\lambda_{0_S}\} \otimes V_C)]. \end{aligned} \quad (3.20)$$

By exploiting the statement of Theorem 2, we can also say that when the commutator of two generators of the original Lie (super)algebra falls into a linear combination involving more than one generator, the intersection between the subsets of the set \tilde{S} could be a non-empty set, which means that the same element(s) will appear in more than one subset of the set \tilde{S} ¹⁰.

Furthermore, we can also observe that the S -expansion procedure does *not always* reproduce an Inönü-Wigner contraction, and this is due to the fact that in the Inönü-Wigner contraction there are some terms in the commutation relations which can go to zero separately, while this cannot happen when one is dealing with the S -expansion, where, in fact, the combination of two-selectors appearing in the left-hand-side of equation (3.15) can only give either zero or a single two-selector. Thus, one can apply our analytic method with the *exception* of the cases in which the S -expansion procedure cannot reproduce the Inönü-Wigner contraction.

We may observe that equation (3.14) can be rewritten in a simpler form (due to the fact that the left hand side produces commutation relations that trivially conduce to the zero element of the set \tilde{S}), which reads

$$[S_{\Delta_A} \otimes V_A, S_{\Delta_B} \otimes V_B] = \left(K_{(\Delta_A)(\Delta_B)}^{(\Delta_C)}(C)_{AB}^C \right) [(S_{\Delta_C} \otimes V_C) \oplus (\{\lambda_{0_S}\} \otimes V_C)], \quad (3.21)$$

so as to highlight the information we need to know about the multiplication rules between the elements in the set \tilde{S} .

We can now proceed with the development of our analytic method. The relation (3.14) gives us a first view on the multiplication rules between the elements of the set \tilde{S} , since it tells us the way in which the different subsets of \tilde{S} combine among each other, that is to say

$$(S_{\Delta_A} \cup \{\lambda_{0_S}\}) \cdot (S_{\Delta_B} \cup \{\lambda_{0_S}\}) \subset S_{\Delta_C} \cup \{\lambda_{0_S}\}, \quad (3.22)$$

where the product “ \cdot ” is the internal product of the set \tilde{S} , and thus between its subsets. According to the relation in (3.21), equation (3.22) can also be rewritten as

$$S_{\Delta_A} \cdot S_{\Delta_B} \subset S_{\Delta_C} \cup \{\lambda_{0_S}\}. \quad (3.23)$$

We have thus exhausted the information coming from the starting (super)algebra \mathcal{G} , and we have gained a first view on the multiplication rules of the elements of the subsets of \tilde{S} . Now we can exploit the information coming from the target (super)algebra, in order to fix some detail on the multiplication rules and to build up the whole multiplication table describing the set \tilde{S} . This step is based on the following *identification criterion*.

¹⁰In the example given in Subsection 4.4, and in particular in Appendix D, we have used this statement; The reader can find the explicit application of this observation in equations (D.57) and (D.58).

3.1 Identification criterion

Until now, we have exploited the information coming from the original (super)algebra.

It is now necessary to understand the structure of the whole multiplication table of the set \tilde{S} . To this aim, the other pieces of information we need to know come from the target Lie (super)algebra. In fact, since at this point, we already know the composition laws between the subsets of \tilde{S} , we can now write the following identification between the S -expanded generators of the initial Lie (super)algebra and the generators of the target one:

$$\tilde{T}_A = T_{A,\alpha} \equiv \lambda_\alpha T_A, \quad (3.24)$$

where T_A are the generators included in the subspace V_A of the starting (super)algebra and \tilde{T}_A are the generators in the subspace \tilde{V}_A of the target (super)algebra, and where $\lambda_\alpha \in \tilde{S}$ is a general element of the set \tilde{S} ¹¹.

We have to perform the identification (3.24) for each element of the set \tilde{S} , associating each element of each subset with the generators in the subspace related to the considered subset, that is to say, in our notation,

$$\tilde{T}_A = \lambda_{(\alpha, \Delta_A)} T_A, \quad (3.25)$$

where $\lambda_{(\alpha, \Delta_A)} \equiv \lambda_\alpha \in S_{\Delta_A}$.

We can observe that in the development of our analytic method, we can perform the whole procedure of association and identification *without* affecting the internal structure of the generators of the starting (super)algebra.

With the identification (3.24), we can link the commutation relations between the generators of the target (super)algebra with the commutation relations of the S -expanded ones, and, factorizing the elements of the set \tilde{S} , we have the chance of fixing the multiplication relations between these elements. To this aim, we first observe that for the target (super)algebra we can write the commutation relations

$$[\tilde{T}_A, \tilde{T}_B] = \tilde{C}_{AB}^C \tilde{T}_C, \quad (3.26)$$

where \tilde{T}_A , \tilde{T}_B , and \tilde{T}_C are the generators in the subspaces \tilde{V}_A , \tilde{V}_B , and \tilde{V}_C of the partition over the target Lie (super)algebra, respectively ($A, B, C \in \{0, \dots, N-1\}$). Here, with \tilde{C}_{AB}^C we denote the structure constants of the target Lie (super)algebra, that is to say $\tilde{C}_{AB}^C \equiv C_{(A,\alpha)(B,\beta)}^{(C,\gamma)}$, in the usual notation. Then, by following the usual S -expansion procedure (see Ref. [5]), since for the initial (super)algebra we can write

$$[T_A, T_B] = C_{AB}^C T_C, \quad (3.27)$$

where we have adopted the same notation used in the case of the target (super)algebra, and where C_{AB}^C are the structure constants of the initial Lie (super)algebra, we are able to write the relations (2.5). We also report them here for completeness:

$$[T_{(A,\alpha)}, T_{(B,\beta)}] = K_{\alpha\beta}^\gamma C_{AB}^C T_{(C,\gamma)}, \quad (3.28)$$

¹¹We have to remember that when performing our analytic method, we are just talking about a general set \tilde{S} , since we do not know yet whether it is, or is not, a semigroup. However, the final check for associativity will tell us if the set \tilde{S} is or is not a semigroup.

namely

$$[\lambda_\alpha T_A, \lambda_\beta T_B] = K_{\alpha\beta}{}^\gamma C_{AB}{}^C \lambda_\gamma T_C, \quad (3.29)$$

where the two-selector is defined by (2.1).

We now write the structure constants of the target (super)algebra in terms of the two-selector and of the structure constants of the starting one, namely, reporting equation (2.6) here for completeness,

$$\tilde{C}_{AB}{}^C \equiv C_{(A,\alpha)(B,\beta)}{}^{(C,\gamma)} = K_{\alpha\beta}{}^\gamma C_{AB}{}^C, \quad (3.30)$$

and we exploit the identification (3.24) in order to write the commutation relations of the target (super)algebra (3.26) in terms of the commutation relations between the S -expanded generators of the starting one, factorizing the elements of the set \tilde{S} out of the commutators. In this way, we get the following relations:

$$[\lambda_\alpha T_A, \lambda_\beta T_B] = K_{\alpha\beta}{}^\gamma C_{AB}{}^C \lambda_\gamma T_C, \quad \longrightarrow \quad \lambda_\alpha \lambda_\beta [T_A, T_B] = K_{\alpha\beta}{}^\gamma C_{AB}{}^C \lambda_\gamma T_C. \quad (3.31)$$

If we now compare the commutation relations (3.31) with the ones of the starting (super)algebra in (3.27), we are able to deduce something more about the multiplication rules between the elements of \tilde{S} , that is to say:

$$\lambda_\alpha \lambda_\beta = \lambda_\gamma. \quad (3.32)$$

We have to repeat this procedure for all the commutation rules of the target (super)algebra, in order to sculpt the multiplication rules between the elements of the set \tilde{S} .

We observe that, during this process, the possible existence of the zero element in the set \tilde{S} , namely λ_{0_S} , can play a crucial role, since, in the case in which the commutation relations of the target (super)algebra read

$$[\tilde{T}_A, \tilde{T}_B] = 0, \quad (3.33)$$

and at the same time from the initial (super)algebra we have

$$[T_A, T_B] \neq 0, \quad (3.34)$$

putting all together the relations

$$[\lambda_\alpha T_A, \lambda_\beta T_B] = \lambda_\alpha \lambda_\beta [T_A, T_B] = C_{AB}{}^C \lambda_\gamma T_C = 0 \quad (3.35)$$

and (3.34), we can conclude that

$$\lambda_\alpha \lambda_\beta = \lambda_{0_S}. \quad (3.36)$$

Thus, at the end of the whole procedure, we are left with the complete multiplication table(s) describing the set(s) \tilde{S} involved in the S -expansion (with either resonance or 0_S -resonant-reduction) process for moving from an initial Lie (super)algebra to a target one.

The final step consist in checking that \tilde{S} is indeed an abelian semigroup. This is done by checking the *associativity* of the multiplication table(s) (one of the properties required by a set to be defined as a semigroup is, in fact, the associative property).

Another very important thing is that in the set of equations (3.4) has another piece of information to give us. For the cases in which we are requiring to this equations the following procedure, for example

$$\dim(V_0)_{S-exp, R.R.} = \dim(V_0) (P - 1 - m), \quad (3.37)$$

$$\dim(V_1)_{S-exp, R.R.} = \dim(V_1) (P - 1 - l), \quad (3.38)$$

$$P = l + m + 1 \quad (3.39)$$

where

$$\dim(V_1) = 0 \quad (3.40)$$

we'll have

$$\dim(V_1)_{S-exp, R.R.} = 0$$

no matter the possible values on the factor $(P - 1 - l)$ it will always be zero, so the remaining system of equations becomes degenerated as follows (for example)

$$\begin{aligned} \dim(V_0)_{S-exp, R.R.} &= \dim(V_0) (P - 1 - m) \\ \dim(V_1)_{S-exp, R.R.} &= 0 \\ P &= l + m + 1 \end{aligned} \quad (3.41)$$

so we have to think on the above in a rather different way to have as equations as unknowns as is possible. This is done realizing our selves that the only way to create the new subspace V_1 is to extract some generators of the non zero part in the original algebra. This is traduced in the set (3.4) like this

$$\dim(V_0)_{S-exp, R.R.} = \dim(V_B)m, \quad (3.42)$$

$$\dim(V_1)_{S-exp, R.R.} = \dim(V_A)l, \quad (3.43)$$

$$\dim(V_0) = \dim(V_A) + \dim(V_B), \quad (3.44)$$

$$P = l + m + 1 \quad (3.45)$$

simplifying the unknown labels

$$A = am \quad (3.46)$$

$$B = bl \quad (3.47)$$

$$P = l + m + 1 \quad (3.48)$$

$$C = a + b \quad (3.49)$$

we have the first solution:

$$P = \frac{1}{2l-1} (2l^2 + 2l - 1), \quad a = \frac{1}{l} (6l - 3), \quad b = \frac{3}{l}, \quad m = \frac{l}{2l-1} \quad (3.50)$$

then, as b must belong to naturals it's necessary that l acquires the numeric values $l = 1, 3$ which make exact the equation system, so we have the second solutions:

$$P = 3, \quad a = 3, \quad b = 3, \quad l = 1, \quad m = 1 \quad (3.51)$$

$$P = \frac{13}{5}, \quad a = 5, \quad b = 1, \quad m = \frac{3}{5} \quad (3.52)$$

from which just (3.51) is consistent with the naturals condition. This represents the case of the Inönü-Wigner for the process $so(2, 2) \rightarrow iso(2(1), 1(2))$ using the semigroup $S_E^{(1)}$

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Now if we have a more general case in which the unique initial space that composites the original algebra we'll find the following system of equations

$$\dim(V_0)_{S-exp, R.R.} = \dim(V_B)m, \quad (3.53)$$

$$\dim(V_1)_{S-exp, R.R.} = \dim(V_A)l, \quad (3.54)$$

$$\dim(V_2)_{S-exp, R.R.} = \dim(V_C)n, \quad (3.55)$$

$$\dim(V_0) = \dim(V_A) + \dim(V_B) + \dim(V_C), \quad (3.56)$$

$$P = l + m + n + 1 \quad (3.57)$$

$$3 = am \quad (3.58)$$

$$3 = bl \quad (3.59)$$

$$6 = cn \quad (3.60)$$

$$P = l + m + n + 1 \quad (3.61)$$

$$9 = a + b + c \quad (3.62)$$

The first two solutions are:

$$\begin{aligned}
I) \quad P &= \frac{1}{6b+b^2n-9bn} (b^2n^2 + b^2n - 9bn^2 - 3bn + 6b - 27n + 18), \\
& a = -\frac{1}{n} (bn - 9n + 6), \\
& c = \frac{6}{n}, \\
& l = \frac{3}{b}, \\
& m = -3\frac{n}{bn-9n+6}
\end{aligned} \tag{3.63}$$

$$\begin{aligned}
II) \quad P &= \frac{5}{3} \\
& a = -b \\
& c = 9 \\
& l = \frac{3}{b} \\
& m = -\frac{3}{b} \\
& n = \frac{2}{3}
\end{aligned} \tag{3.64}$$

this is not at all undefined because we have on hand the fact that all the terms in most belong to **naturals numbers** so this implies that *II* are discarded and

$$cn = 6 \tag{3.65}$$

$$lb = 3 \tag{3.66}$$

so as we know all the variables belong to **naturals** so it's naturally necessary that $l=1, 3$ and $b = 3, 1$ correspondingly. Is important to emphasize that here we obtain at the same time two unknown variables despite the undefined system of equations and the fact that we have more than one option is convenient because we ensure a little more that an answer will be found. So let's choose the first answer $l = 1$ and $b = 3$

$$3 = am \tag{3.67}$$

$$6 = cn \tag{3.68}$$

$$P = 1 + m + n + 1 \tag{3.69}$$

$$9 = a + 3 + c . \tag{3.70}$$

Solution is:

$$P = \frac{1}{2m-1} (2m^2 + 5m - 2), \tag{3.71}$$

$$a = \frac{3}{m}, \tag{3.72}$$

$$c = \frac{1}{m} (6m - 3), \tag{3.73}$$

$$n = \frac{2m}{2m-1} \tag{3.74}$$

so using the **naturals** condition we get immediatelly the full set of numeric values for the unknown variables

$$\begin{aligned}
\frac{2m}{2m-1} &\in \mathbf{N} \\
&\Rightarrow \\
m &= 1 \\
&\Rightarrow n = 2, c = 3, a = 3, P = 5
\end{aligned} \tag{3.75}$$

with $n = 1, 2, \dots, \infty$. For the other branch $l = 3$ and $b = 1$ we get the two exact solutions $P = \frac{31}{5}, a = 3, c = 5, n = \frac{6}{5}$ and $P = \frac{55}{7}, a = 1, c = 7, n = \frac{6}{7}$

so that branch is discarded by the **naturals** condition. In summary the system of equation acquires **analytically** the unique numeric solution

$$a = 3, b = 3, c = 3, m = 1, n = 2, l = 1, P = 5 \tag{3.76}$$

this implies that there are a possible S -expansion for to pass from the (sample) Lie algebra $\mathcal{G} = V_0$ to $\mathcal{G}_{S\text{-exp}} = \tilde{V}_0 \oplus \tilde{V}_1 \oplus \tilde{V}_2$ with a semigroup at least $P = 5$ elements, with a partition $\sqcup_{\Delta} \{S_{l_{\Delta}}\} = \{S_{m_a}\} \sqcup \{S_{l_b}\} \sqcup \{S_{n_c}\} = \{S_{1_0}\} \sqcup \{S_{1_1}\} \sqcup \{S_{2_2}\}$ and that way to split the original algebra in three subspaces $\tilde{V}_0 \oplus \tilde{V}_1 \oplus \tilde{V}_2$ with cardinality $a = 3, b = 3, c = 3, m = 1$ correspondingly.

Let's go beyond in the generalization of the possible proces that we can achieve with the S -expansion, now in the case that there are two subspaces V_0, V_1 , for example:

$$\dim(V_0)_{S\text{-exp, R.R.}} = \dim(V_A)m, \tag{3.77}$$

$$\dim(V_1)_{S\text{-exp, R.R.}} = \dim(V_B)l, \tag{3.78}$$

$$\dim(V_2)_{S\text{-exp, R.R.}} = \dim(V_C)n, \tag{3.79}$$

$$\dim(V_3)_{S\text{-exp, R.R.}} = \dim(V_E)l, \tag{3.80}$$

$$\dim(V_4)_{S\text{-exp, R.R.}} = \dim(V_F)l, \tag{3.81}$$

$$\dim(V_0) = \dim(V_A) + \dim(V_B) + \dim(V_C), \tag{3.82}$$

$$\dim(V_1) = \dim(V_A) + \dim(V_B) + \dim(V_C) \tag{3.83}$$

$$P = l + m + n + 1 \tag{3.84}$$

$$2 = am \quad (3.85)$$

$$3 = bl \quad (3.86)$$

$$4 = cn \quad (3.87)$$

$$1 = fl \quad (3.88)$$

$$2 = go \quad (3.89)$$

$$3 = a + b + c \quad (3.90)$$

$$3 = f + g \quad (3.91)$$

$$P = l + m + n + o + 1 \quad (3.92)$$

The solution is:

$$\emptyset \quad \text{if} \quad -go + 2 \neq 0 \quad (3.93)$$

and

$$P = \frac{1}{6m-2o+9mo^2-15mo+3o^2} \begin{pmatrix} 6m-2o \\ -6mo^2-15m^2o \\ +9mo^3+9m^2o^2 \\ -10mo+6m^2 \\ +2o^2+3o^3 \end{pmatrix}, \quad \text{if} \quad \begin{matrix} -go+2=0 \\ \wedge \\ o \neq 0 \end{matrix} \quad (3.94)$$

$$\begin{matrix} a = \frac{2}{m}, \\ b = \frac{1}{o}(9o-6), \\ c = \frac{1}{mo}(6m-2o-6mo), \\ f = \frac{1}{o}(3o-2), \\ l = \frac{o}{3o-2}, \\ n = 2m \frac{o}{3m-o-3mo} \end{matrix}$$

according to this we know that

$$\begin{aligned} l &= \frac{o}{3o-2} \wedge b = \frac{1}{o}(9o-6) \\ \implies \\ o &= \{1\} \cap o = \{1, 2, 3, 6\} \end{aligned} \quad (3.95)$$

$$\implies \\ o = 1 \quad (3.96)$$

$$b = 3 \quad (3.97)$$

$$f = 1 \quad (3.98)$$

$$g = 2 \quad (3.99)$$

$$m = \{1, 2\} \quad (3.100)$$

$$a = \{2, 1\} \quad (3.101)$$

but, by the **naturals** condition

$$\begin{aligned}
c &= \frac{1}{mo} (6m - 2o - 6mo) \in \mathbf{N} \\
&\implies \\
-2 &\in \mathbf{N} m \\
&\implies \\
m &\notin
\end{aligned} \tag{3.102}$$

which is contradictory so this system doesn't have a natural solution and has to be discarded. This implies that there are not a possible S -expansion to pass from the (sample) Lie algebra $\mathcal{G} = V_0 \oplus V_1$ to $\mathcal{G}_{S\text{-exp}} = V_0 \oplus V_1 \oplus V_2 \oplus V_3 \oplus V_4$ by means of a S -expansion following the given above requirements.

With this analysis we can finally know that it's possible in some cases to obtain a different quantity of subspaces between the original Lie algebra and the S -expanded one but always respecting the identification criterion, that means, the S -expanded subspaces that we create from the original ones and that exceed the number of subspaces of the original Lie algebra must be considered as the same nature in the sense of the action that perform over a vectorial space. For example if in the original one we had one subspace of rotations the new subspaces created from this must be rotations too.

3.2 A note on associativity

A note on associativity

The last step consists in analyzing the associative property of the set \tilde{S} . The check for associativity can be rather tedious if performed by hand, but, fortunately, it can be implemented by means of a simple computational algorithm. In fact, by mapping the elements λ_i of the set \tilde{S} to the set of the integer numbers $\lambda_i \leftrightarrow i \in \mathbb{N}$, it is possible to store the multiplication table of \tilde{S} as a matrix M , in a form in which its elements are given by $\lambda_j \lambda_k = \lambda_i \equiv M(j, k) = i$, where i is the index associated with the element λ_i . Associativity can now be easily tested by checking that, for any i, j , and k , the following relation holds:

$$M(M(i, j), k) = M(i, M(j, k)). \tag{3.103}$$

After the check for associativity, the degeneracy of the multiplication table(s) obtained in the analytic procedure after having applied the identification criterion is fixed, and we are left with one (or more) semigroup(s).

However, in Section 4, we will develop a particular example of application of our analytic method in which, in order to reach the target Bianchi Type II algebra from the Bianchi Type I algebra, the structure of semigroup is *not* necessary, since the procedure can be performed

with abelian set(s), without requiring associativity. This is due to the fact that, in that case, the Jacobi identities of both the mentioned algebras are trivially satisfied (each term of the Jacobi identities is equal to zero). In this work, we just mention this particular case, generalizing the result presented in the literature (see Ref. [20]).

4 Examples of application

In this section, we give some example of application of the analytic method previously developed. We start with a simple example involving the Bianchi Type I and the Bianchi Type II algebras, and then we move to more complicated cases. In particular, the last example presented in this section involves the supersymmetric Lie algebra $osp(32/1)$ and the hidden superalgebra underlying $D = 11$ supergravity, largely discussed in [38, 39].

The details of the calculations are treated in the Appendix, while in the following we report and discuss our main results.

4.1 From the Bianchi Type I algebra (BTI) to the Bianchi Type II one (BTII)

In the following, we apply the method developed in Section 3 in order to find the possible semigroup(s) leading from the non-trivial Bianchi Type I algebra (BTI) to the Bianchi Type II (BTII) one. To this aim, we first of all analyze the structures of the initial algebra and of the target one. The only commutator different from zero for the BTI algebra is

$$[X_1, X_2] = X_1, \quad (4.1)$$

where X_1 and X_2 are the generators of the BTI algebra. For the BTII algebra, instead, we have

$$[Y_1, Y_2] = 0, \quad (4.2)$$

$$[Y_1, Y_3] = 0, \quad (4.3)$$

$$[Y_2, Y_3] = Y_1, \quad (4.4)$$

where Y_1 , Y_2 , and Y_3 are the generators of the BTII algebra. The details of the calculations are treated in Appendix A, while in the following we report our results.

Performing the steps described in Section 3, we obtain the multiplication tables

	λ_a	λ_b	λ_c	λ_{0_S}	
λ_a	$\lambda_{a,0_S}$	λ_{0_S}	λ_b	λ_{0_S}	
λ_b	λ_{0_S}	$\lambda_{a,0_S}$	$\lambda_{a,0_S}$	λ_{0_S}	
λ_c	λ_b	$\lambda_{a,0_S}$	$\lambda_{a,0_S}$	λ_{0_S}	
λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	

(4.5)

We can now perform the following identification:

$$\lambda_a = \lambda_2, \quad \lambda_b = \lambda_3, \quad \lambda_c = \lambda_1, \quad \lambda_{0_S} = \lambda_4. \quad (4.6)$$

Thus, we can rewrite tables (4.5) as follows (where the elements are written in the usual order):

$$\begin{array}{c|cccc}
& \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 \\
\hline
\lambda_1 & \lambda_{2,4} & \lambda_3 & \lambda_{2,4} & \lambda_4 \\
\lambda_2 & \lambda_3 & \lambda_{2,4} & \lambda_{2,4} & \lambda_4 \\
\lambda_3 & \lambda_{2,4} & \lambda_{2,4} & \lambda_{2,4} & \lambda_4 \\
\lambda_4 & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4
\end{array} \tag{4.7}$$

These are the multiplication tables of the possible sets \tilde{S} 's involved in the S -expansion, 0_S -resonant-reduced procedure from the BTI algebra to the BTII one. Here we clearly see that the tables described in (4.7) also include abelian sets that cannot be defined as semigroup, since they do not possess the associative property. Fortunately, for both the BTI and BTII algebras, each term of the Jacobi identity is equal to zero (thus, the Jacobi identity is trivially satisfied), and thus each possible combination of elements in (4.7) is valid for describing an expansion procedure involving both resonance and reduction, without the necessity of requiring associativity. Thus, the multiplication tables (4.7) generalize the result previously obtained in [20].

We can also perform a last step, in order to find the table(s) in (4.5) which describe semigroup(s). This step consists in exploiting the required property of associativity, in order to fix the degeneracy on the multiplication tables (4.5) and finding the semigroup(s) involved in the process. The calculation is rather tedious to be performed by hand, and we have done it with a computational algorithm. For completeness, here we report only the significant relations for checking associativity by hand and understanding which are the semigroups in (4.5):

$$(\lambda_c \lambda_c) \lambda_b = \lambda_c (\lambda_c \lambda_b) \Rightarrow \lambda_c \lambda_b = \lambda_{0_S}, \tag{4.8}$$

$$(\lambda_c \lambda_a) \lambda_a = \lambda_c (\lambda_a \lambda_a) \Rightarrow \lambda_a \lambda_a = \lambda_{0_S}, \tag{4.9}$$

$$(\lambda_c \lambda_b) \lambda_b = \lambda_c (\lambda_b \lambda_b) \Rightarrow \lambda_b \lambda_b = \lambda_{0_S}. \tag{4.10}$$

After having checked associativity, we are thus left with the only degeneracy

$$\lambda_c \lambda_c = \lambda_{a,0_S}. \tag{4.11}$$

We can now substitute the index $a, b, c, 0_S$ with numbers. We perform again the identification (4.6), and we write the multiplication tables thus obtained in terms of λ_i , with $i = 1, 2, 3, 4$, in the usual order:

$$\begin{array}{c|cccc}
& \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 \\
\hline
\lambda_1 & \lambda_{2,4} & \lambda_3 & \lambda_4 & \lambda_4 \\
\lambda_2 & \lambda_3 & \lambda_4 & \lambda_4 & \lambda_4 \\
\lambda_3 & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4 \\
\lambda_4 & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4
\end{array} \tag{4.12}$$

We observe that the abelian, commutative and associative tables (4.12) include the multi-

multiplication table of the semigroup S_{N_2} described in [20], namely

$$\begin{array}{c|cccc}
 & \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 \\
 \hline
 \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 & \lambda_4 \\
 \lambda_2 & \lambda_3 & \lambda_4 & \lambda_4 & \lambda_4 \\
 \lambda_3 & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4 \\
 \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4
 \end{array} \tag{4.13}$$

which represents a possible semigroup for moving from a BTI algebra to a BTII algebra, through a 0_S -resonant-reduction procedure. The degeneracy appearing in (4.12) (namely $\lambda_1\lambda_1 = \lambda_{2,4}$) shows us that there are two possible semigroups able to give the same result (one of them is the same described in [20], S_{N_2} , while the other one is a new result that we have obtained with our analytic procedure).

We have thus given an example in which the method described in Section 3 allows us to find the semigroups for moving from the BTI algebra to a S -expanded, 0_S -resonant-reduced one (BTII), once the partitions over subspaces have been properly chosen.

We can now try to achieve the same result, by considering an S -expansion with only a *resonant* structure (relaxing the reduction condition). To this aim, we study the system (3.7), which, in this case, is solved by

$$\tilde{P} = 3, \quad \Delta_0 = 1, \quad \Delta_1 = 2. \tag{4.14}$$

Then, performing the usual procedure (see Section 3) and assuming the same identification presented in the detailed calculations for the previous case (see Appendix A), namely

$$\lambda_a X_2 = Y_3 \tag{4.15}$$

$$\lambda_b X_1 = Y_1 \tag{4.16}$$

$$\lambda_c X_1 = Y_2, \tag{4.17}$$

we can reach the multiplication rules between the elements of the set \tilde{S} , after having faced the particular situation in which

$$[Y_1, Y_3] = 0, \tag{4.18}$$

$$[\lambda_b X_1, \lambda_a X_3] = 0, \tag{4.19}$$

$$\lambda_b \lambda_a [X_1, X_2] = 0, \tag{4.20}$$

where $[X_1, X_2] = X_1 \neq 0$. As we can see in equation (4.18), the generators Y_1 and Y_3 of the target algebra must commute, while the generators X_1 and X_2 of the starting algebra do not commute; so, the only way for reaching a consistent multiplication rule between the elements λ_a and λ_b consists in adding a zero element in the set \tilde{S} involved in the process, such that

$$\lambda_b \lambda_a = \lambda_{0_S}. \tag{4.21}$$

The inclusion of the zero element is consistent, since this modification just affects the variable \tilde{P} in the system (3.7), which increases of +1 (namely, $\tilde{P} = 4$). In this way, the multiplication

table of the set \tilde{S} acquires both a new row and a new column, without affecting associativity, in the case of a semigroup table.

We can thus conclude that, in this case, our analytic method shows us the necessity of including a 0_S -reduction to the resonant process too. Thus, we can reach the following multiplication rules:

$$\begin{aligned}\lambda_a \lambda_a &= \lambda_a, \\ \lambda_c \lambda_a &= \lambda_b, \\ \lambda_{b,c} \lambda_{b,c} &= \lambda_a, \\ \lambda_b \lambda_a &= \lambda_{0_S},\end{aligned}\tag{4.22}$$

and the multiplication table, after having performed the identification

$$\lambda_a = \lambda_2, \quad \lambda_b = \lambda_3, \quad \lambda_c = \lambda_1, \quad \text{with the extra zero element } \lambda_{0_S} = \lambda_4,\tag{4.23}$$

reads

$$\begin{array}{c|ccc|c|ccc} & \lambda_1 & \lambda_2 & \lambda_3 & & \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 \\ \hline \lambda_1 & \lambda_2 & \lambda_3 & \lambda_2 & \longrightarrow & \lambda_1 & \lambda_2 & \lambda_3 & \lambda_2 & \lambda_4 \\ \lambda_2 & \lambda_3 & \lambda_2 & \lambda_4 & & \lambda_2 & \lambda_3 & \lambda_2 & \lambda_4 & \lambda_4 \\ \lambda_3 & \lambda_2 & \lambda_4 & \lambda_2 & & \lambda_3 & \lambda_2 & \lambda_4 & \lambda_2 & \lambda_4 \\ & & & & & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4 & \lambda_4\end{array}\tag{4.24}$$

Let us finally observe that table (4.24), which is abelian (but *not* associative), is included in the multiplication tables (4.7), previously obtained in the context of 0_S -resonant-reduction.

This last table has its significance because lead us to a very interesting conclusion according to the ref [5] , in particular to the theorem III.1:

Theorem III.1 Let $S = \{\lambda_\alpha\}$ be an abelian semigroup with 2-selector $K_{\alpha\beta}$ and \mathcal{G} a Lie (super)algebra with basis $\{T_p\}$ and structure constants $C_{pq}{}^r$. Denote a basis element of the direct product $S \otimes \mathcal{G}$ by $T_{(p,\alpha)} = \lambda_\alpha T_p$ and consider the induced commutator $[T_{(p,\alpha)}, T_{(q,\beta)}] = \lambda_\alpha \lambda_\beta [T_p, T_q]$. Then $S \otimes \mathcal{G}$ is also a Lie (super)algebra with structure constants

$$C_{(p,\alpha)(q,\beta)}{}^{(r,\gamma)} = K_{\alpha\beta}{}^\gamma C_{pq}{}^r$$

For the present example we have to make the following observation looking at the Jacobi identity

$$[T_p, [T_q, T_r]] + [T_q, [T_r, T_p]] + [T_r, [T_p, T_q]] = 0$$

for the S-expanded version

$$[\lambda_\alpha T_p, [\lambda_\beta T_q, \lambda_\gamma T_r]] + [\lambda_\beta T_q, [\lambda_\gamma T_r, \lambda_\alpha T_p]] + [\lambda_\gamma T_r, [\lambda_\alpha T_p, \lambda_\beta T_q]] = 0$$

to demonstrate that $S \otimes \mathcal{G}$ satisfy the Jacobi identity and consequently (a fundamental property of a Lie algebra) it has been said that a necessary condition over the set of elements $S = \{\lambda\}$ is the associativity because this property allow us to rewrite the above expression in the following form

$$\lambda_\alpha \lambda_\beta \lambda_\gamma [T_p, [T_q, T_r]] + \lambda_\beta \lambda_\gamma \lambda_\alpha [T_q, [T_r, T_p]] + \lambda_\gamma \lambda_\alpha \lambda_\beta [T_r, [T_q, T_p]] = 0$$

$$\lambda_\alpha \lambda_\beta \lambda_\gamma [T_p, [T_q, T_r]] + \lambda_\alpha \lambda_\beta \lambda_\gamma [T_q, [T_r, T_p]] + \lambda_\alpha \lambda_\beta \lambda_\gamma [T_r, [T_q, T_p]] = 0$$

$$\lambda_\alpha \lambda_\beta \lambda_\gamma \underbrace{([T_p, [T_q, T_r]] + [T_q, [T_r, T_p]] + [T_r, [T_q, T_p]])}_{=0} = 0$$

where in the second row we have used the associativity property imposed over the set $S = \{\lambda\}$ to factorize the triple multiplication $\lambda_\alpha \lambda_\beta \lambda_\gamma$ and ensure the last equality.

However this is not always a *necessary condition* as we will see from this example. form $[X_1, X_2] = X_1$ we have

$$[T_1, [T_1, T_2]] + [T_1, [T_2, T_1]] + [T_2, [T_1, T_1]] = 0$$

$$\underbrace{[T_1, [T_1, T_2]]}_{=0} + \underbrace{[T_1, [T_2, T_1]]}_{=0} + \underbrace{[T_2, [T_1, T_1]]}_{=0} = 0$$

so we will have for the S-expanded version

$$[\lambda_\alpha T_1, [\lambda_\beta T_1, \lambda_\gamma T_2]] + [\lambda_\beta T_1, [\lambda_\gamma T_2, \lambda_\alpha T_1]] + [\lambda_\gamma T_2, [\lambda_\alpha T_1, \lambda_\beta T_1]] = 0$$

$$\lambda_\alpha \lambda_\beta \lambda_\gamma \underbrace{[T_1, [T_1, T_2]]}_{=0} + \lambda_\beta \lambda_\gamma \lambda_\alpha \underbrace{[T_1, [T_2, T_1]]}_{=0} + \lambda_\gamma \lambda_\alpha \lambda_\beta \underbrace{[T_2, [T_1, T_1]]}_{=0} = 0$$

so the last equality is ensured without impose associativity on the set $S = \{\lambda\}$. In base of this we establish the following theorem:

Theorem 3. Let $S = \{\lambda_\alpha\}$ be an abelian, discrete and finite set (magma) $S = \{\lambda\}$ and \mathcal{G} a Lie (super)algebra with basis $\{T_p\}$ and structure constants C_{pq}^r . Denote a basis element of the direct product $S \otimes \mathcal{G}$ by $T_{(p,\alpha)} = \lambda_\alpha T_p$ and consider the induced commutator $[T_{(p,\alpha)}, T_{(q,\beta)}] = \lambda_\alpha \lambda_\beta [T_p, T_q]$. If there are two subsets of generators in \mathcal{G} denoted by $\mathcal{I} = \{T_i\}$ and $T_0 = \{T_{0_i}\}$, where:

$$\#\mathcal{I} \geq 3$$

$$\#T_0 \geq 1$$

$$[T_i, T_{0_i}] = 0$$

$$\begin{aligned} [T_i, T_j] &= T_{0_k} \\ k &\neq i, j \\ i, j, k &\in \mathcal{I} \end{aligned}$$

holds and $\mathcal{I} \cap T_0 = \emptyset$ is sufficient but not necessary. Then the product space $S \otimes \mathcal{G}$ will be a Lie algebra without imposing complete associativity on the set S .

Proof:

$$[\lambda_\alpha T_i, [\lambda_\beta T_j, \lambda_\gamma T_k]] + [\lambda_\beta T_j, [\lambda_\gamma T_k, \lambda_\alpha T_i]] + [\lambda_\gamma T_k, [\lambda_\alpha T_i, \lambda_\beta T_j]] = 0$$

$$(\lambda_\alpha \lambda_\beta \lambda_\gamma) [T_i, [T_j, T_k]] + (\lambda_\beta \lambda_\gamma \lambda_\alpha) [T_j, [T_k, T_i]] + (\lambda_\gamma \lambda_\alpha \lambda_\beta) [T_k, [T_i, T_j]] = 0$$

$$(\lambda_\alpha \lambda_\beta \lambda_\gamma) \underbrace{C_{jk}^{0_i} [T_i, T_{0_i}]}_{=0} + (\lambda_\beta \lambda_\gamma \lambda_\alpha) \underbrace{C_{ki}^{0_j} [T_j, T_{0_j}]}_{=0} + (\lambda_\gamma \lambda_\alpha \lambda_\beta) \underbrace{C_{ij}^{0_k} [T_k, T_{0_k}]}_{=0} = 0$$

for every set $\mathcal{I} \in \mathcal{G}$ and without the necessary factorization of the triple set product. This implies that the condition (for factorization)

$$\lambda_\alpha \lambda_\beta \lambda_\gamma = \lambda_\beta \lambda_\gamma \lambda_\alpha = \lambda_\gamma \lambda_\alpha \lambda_\beta$$

It is not necessary either. \square

So the associativity of the set(s) $S = \{\lambda\}$ is sufficient but not necessary in all these cases.

4.2 $iso(2, 1)$ from the 0_S -resonant-reduction of $so(2, 2)$

In this example, our aim is to find the multiplication table(s) of the semigroup(s) connecting the Lie algebras $so(2, 2)$ and $iso(2, 1)$ in three dimensions, through a 0_S -resonant-reduction process, after having properly chosen the partitions over subspaces.

We can write $so(2, 2) = \{J_i, P_i\}$, with $i = 1, 2, 3$, and $iso(2, 1) = \{\tilde{J}_i, \tilde{P}_i\}$, with $i = 1, 2, 3$, where we have considered $J^i = \frac{1}{2}\epsilon^{ijk} J_{jk}$, according to the notation used in [44]. The commutation relations between the generators of the starting $so(2, 2)$ algebra can be simply written as

$$[J_i, J_j] = \epsilon_{ijk} J^k, \quad (4.25)$$

$$[J_i, P_j] = \epsilon_{ijk} P^k, \quad (4.26)$$

$$[P_i, P_j] = \epsilon_{ijk} J^k, \quad (4.27)$$

where $i, j, k, \dots = 1, 2, 3$, and the commutation relations between the generators of the target $iso(2, 1)$ algebra can be written as

$$[\tilde{J}_i, \tilde{J}_j] = \epsilon_{ijk} \tilde{J}^k, \quad (4.28)$$

$$[\tilde{J}_i, \tilde{P}_j] = \epsilon_{ijk} \tilde{P}^k, \quad (4.29)$$

$$[\tilde{P}_i, \tilde{P}_j] = 0, \quad (4.30)$$

where, again, $i, j, k, \dots = 1, 2, 3$. Thus, following the procedure described in Section 3, we reach the multiplication table

	λ_0	λ_1	λ_2	
λ_0	λ_0	λ_1	λ_2	
λ_1	λ_1	λ_2	λ_2	
λ_2	λ_2	λ_2	λ_2	

(4.31)

The detailed calculations are treated in Appendix B, while in the following we discuss our result.

Table (4.31) is an abelian, commutative and associative multiplication table (the check for associativity in this case is simple). Thus, we are left with the semigroup that allows us to move from the Lie algebra $so(2, 2)$ to the Lie algebra $iso(2, 1)$ one through 0_S -resonant-reduction, just performing the analytic procedure described in Section 3. We have found out that a single semigroup (with respect to the chosen partitions) is involved in the process, and it corresponds to the well known semigroup $S_E^{(1)}$, which is given by

$$\lambda_\alpha \lambda_\beta = \begin{cases} \lambda_{\alpha+\beta}, & \text{when } \alpha + \beta \leq 2, \\ \lambda_2, & \text{when } \alpha + \beta > 2. \end{cases} \quad (4.32)$$

As we can see, table (4.31) perfectly fits this description.

4.3 The Maxwell algebra (\mathcal{M}) as a 0_S -resonant-reduction of the Anti-de Sitter (AdS) Lie algebra

With the analytic procedure described in Section 3, we can find the semigroup linking the Anti-de Sitter (AdS) and the Maxwell (\mathcal{M}) algebras, through the S -expansion (0_S -resonant-reduction) procedure. In the following, we will show that it is exactly the one obtained in [22–24], that is to say the semigroup $S_E^{(2)}$, which satisfies the multiplication law

$$\lambda_\alpha \lambda_\beta = \begin{cases} \lambda_{\alpha+\beta}, & \text{when } \alpha + \beta \leq 3, \\ \lambda_3, & \text{when } \alpha + \beta > 3. \end{cases} \quad (4.33)$$

We start with the analysis of the two mentioned algebras. The generators of the AdS

algebra are $\{J_{ab}, P_a\}$, and they satisfy the commutation relations

$$[J_{ab}, J_{cd}] = \eta_{bc}J_{cd} - \eta_{ac}J_{bd} - \eta_{bd}J_{ac} + \eta_{ad}J_{bc}, \quad (4.34)$$

$$[J_{ab}, P_c] = \eta_{bc}P_a - \eta_{ac}P_b, \quad (4.35)$$

$$[P_a, P_b] = J_{ab}. \quad (4.36)$$

The generators of the Maxwell algebra \mathcal{M} are $\{\tilde{J}_{ab}, \tilde{P}_a, \tilde{Z}_{ab}\}$, and they satisfy the following commutation relations

$$[\tilde{J}_{ab}, \tilde{Z}_{cd}] = \eta_{bc}\tilde{Z}_{cd} - \eta_{ac}\tilde{Z}_{bd} - \eta_{bd}\tilde{Z}_{ac} + \eta_{ad}\tilde{Z}_{bc}, \quad (4.37)$$

$$[\tilde{Z}_{ab}, \tilde{P}_a] = 0, \quad (4.38)$$

$$[\tilde{Z}_{ab}, \tilde{Z}_{cd}] = 0, \quad (4.39)$$

$$[\tilde{J}_{ab}, \tilde{J}_{cd}] = \eta_{bc}\tilde{J}_{cd} - \eta_{ac}\tilde{J}_{bd} - \eta_{bd}\tilde{J}_{ac} + \eta_{ad}\tilde{J}_{bc}, \quad (4.40)$$

$$[\tilde{J}_{ab}, \tilde{P}_c] = \eta_{bc}\tilde{P}_a - \eta_{ac}\tilde{P}_b, \quad (4.41)$$

$$[\tilde{P}_a, \tilde{P}_b] = \tilde{Z}_{ab}. \quad (4.42)$$

We observe that a particular characteristic of the Maxwell algebra is given by the relation

$$[\tilde{P}_a, \tilde{P}_b] = \tilde{Z}_{ab}, \quad (4.43)$$

and that \tilde{Z}_{ab} commutes with all generators of the algebra, except the Lorentz generators J_{ab} .

Interestingly, the Maxwell algebra \mathcal{M} can be obtained with an Inönü-Wigner contraction of the *AdS*-Lorentz algebra¹³ (of which the Lorentz type algebra $\mathcal{L} = \{J_{ab}, Z_{ab}\}$ is a subalgebra), whose supersymmetric extension was deeply studied in Ref. [35] in the context of the supersymmetry invariance of a supergravity theory in the presence of a non-trivial boundary.

The details of the calculations involved in this example are reported in Appendix C, while in the following we discuss our main results.

By performing the analytic procedure described in Section 3, we reach the multiplication table

	λ_0	λ_1	λ_2	λ_3	
λ_0	λ_0	λ_1	λ_2	λ_3	
λ_1	λ_1	λ_2	λ_3	λ_3	
λ_2	λ_2	λ_3	λ_3	λ_3	
λ_3	λ_3	λ_3	λ_3	λ_3	

(4.44)

This table represents an abelian, commutative and associative semigroup, that is exactly the well known semigroup $S_E^{(2)}$ found in [22–24].

¹³This can be easily proved by performing on the *AdS*-Lorentz (super)algebra (the supersymmetric extension of the *AdS*-Lorentz algebra is displayed in Ref. [35]) the following redefinition of the generators $J_{ab} \rightarrow J_{ab}$, $Z_{ab} \rightarrow \frac{1}{\bar{e}}Z_{ab}$, $P_a \rightarrow \frac{1}{\bar{e}}P_a$, ($Q_\alpha \rightarrow \frac{1}{\bar{e}}Q_\alpha$), which provides us with the Maxwell (super)algebra (*s*) \mathcal{M} in the limit $\bar{e} \rightarrow 0$ (here we have relaxed, for simplicity, the notation with the symbol “tilde” above the generators).

4.4 From the supersymmetric Lie algebra $osp(32/1)$ to the hidden superalgebra underlying $D = 11$ supergravity

With this example, we move to *superalgebras*, and in particular we concentrate on the supersymmetric Lie algebra $osp(32/1)$ and on the hidden superalgebra underlying supergravity in eleven dimensions.

Simple supergravity in $D = 11$ was first constructed in [36]. The bosonic field content of $D = 11$ supergravity is given by the metric $g_{\mu\nu}$ and by a 3-index antisymmetric tensor $A_{\mu\nu\rho}$ ($\mu, \nu, \rho, \dots = 0, 1, \dots, D - 1$); The theory also presents a single Majorana gravitino Ψ_μ in the fermionic sector. By dimensional reduction (as it was shown in [37]), the theory yields $\mathcal{N} = 8$ supergravity in four dimensions, which is considered a possibly viable unification theory of all interactions.

An important task to accomplish was the identification of the supergroup underlying the theory, and allowing the unification of all elementary particles in a single supermultiplet, since a supergravity theory whose supergroup is unknown is an incomplete one.

The need for a supergroup was already felt by the inventors of the theory, and in [36] the authors proposed $osp(32/1)$ as the most likely candidate. However, the field $A_{\mu\nu\rho}$ of the Cremmer-Julia-Scherk theory is a 3-form rather than a 1-form, and therefore it cannot be interpreted as the potential of a generator in a supergroup.

The structure of this same theory was then reconsidered in [38, 39], in the Free Differential Algebra (FDA) framework, using the superspace geometric approach. In [38], the supersymmetric FDA was also analyzed in order to see whether the FDA formulation could be interpreted in terms of an ordinary Lie superalgebra (in its dual Maurer-Cartan formulation), introducing the notion of Cartan integrable systems. This was proven to be true, and the existence of a hidden superalgebra underlying the theory was presented for the first time (the authors got a dichotomic solution, consisting in two different supergroups, whose 1-form potentials can be alternatively used to parametrize the 3-form).

This hidden superalgebra includes, as a subalgebra, the super-Poincaré algebra of the eleven-dimensional theory, but it also involves two extra bosonic generators $Z^{ab}, Z^{a_1 \dots a_5}$ ($a, b, \dots = 0, 1, \dots, 10$), commuting with the 4-momentum P_a and having appropriate commutators with the $D = 11$ Lorentz generators J_{ab} . The generators that commute with all the superalgebra but the Lorentz generators can be named “almost central”.

Furthermore, to close the algebra, an extra nilpotent fermionic generator Q' must be included. In the following, we will replace the notation in [38, 39] as follows

$$Z^{ab} \rightarrow \tilde{Z}^{ab}, \quad (4.45)$$

$$Z^{a_1 \dots a_5} \rightarrow \tilde{Z}^{a_1, \dots, a_5}, \quad (4.46)$$

$$Q' \rightarrow \tilde{Q}', \quad (4.47)$$

in order to be able to recognize the generators of the target superalgebra from the generators of starting one, as we have previously done along the paper.

The bosonic generators Z^{ab} and $Z^{a_1 \dots a_5}$ were understood as p -brane charges, sources of dual potentials [40, 41]. The role played by the extra fermionic generator Q' was much

less investigated, and the most relevant contributions were given first in [42], and then in particular in [43], where the results in [38] were further analyzed and generalized.

Recently, in [39], the authors have shown that, as the generators of the hidden super Lie algebra span the tangent space of a supergroup manifold, then, in the geometrical approach, the fields are naturally defined in an enlarged manifold, corresponding to the supergroup manifold, where all the invariances of the FDA are diffeomorphisms, generated by Lie derivatives.

The extra spinor 1-form involved in the construction of the hidden superalgebra allows, in a dynamical way, the diffeomorphisms in the directions spanned by the almost central charges to be particular gauge transformations, so that one obtains the ordinary superspace as the quotient of the supergroup over the fiber subgroup of gauge transformations.

We now want to show that, with the analytic method developed in Section 3, we are able to find the semigroup which is involved in the S -expansion (0_S -resonant-reduction) procedure for moving from the original $osp(32/1)$ Lie algebra to the hidden superalgebra underlying supergravity in eleven dimensions.

This achievement tell us that the method described in [38, 39], which is based on the development of the FDA in terms of 1-forms (the Maurer-Cartan formulation of the FDA has a dual description in terms of commutation relations of the considered Lie algebra, as it is shown in [7]), lead to the same result (that is to say, to the same hidden superalgebra) that can be found performing a S -expansion (0_S -resonant-reduction) procedure from $osp(32/1)$, with an appropriate semigroup. We will display the multiplication table of the mentioned semigroup in the following, and we will see that it is the semigroup $S_E^{(3)}$, which satisfies the multiplication rules

$$\lambda_\alpha \lambda_\beta = \begin{cases} \lambda_{\alpha+\beta}, & \text{when } \alpha + \beta \leq 4, \\ \lambda_4, & \text{when } \alpha + \beta > 4. \end{cases} \quad (4.48)$$

The same result was previously achieved in [5], where the authors showed how to perform a S -expansion from $osp(32/1)$ to a D'Auria-Fré-like superalgebra (with the same structure of the D'Auria-Fré superalgebra, but with different details), using $S_E^{(3)}$ as semigroup. This analogy confirms and corroborates the analytic method developed in the present work.

In this example, we also analyze the link between $osp(32/1)$ and another superalgebra included in the dichotomic solution found in [38, 39], in which the translations and the fermionic generators, respectively denoted by \tilde{P}_a and \tilde{Q} , commute. We will see that the supersymmetric Lie algebra $osp(32/1)$ and this particular hidden superalgebra are linked by a S -expansion (0_S -resonant-reduction) procedure, in which the semigroup involved in the process is the semigroup $S_E^{(2)}$, which satisfies the multiplication rules

$$\lambda_\alpha \lambda_\beta = \begin{cases} \lambda_{\alpha+\beta}, & \text{when } \alpha + \beta \leq 3, \\ \lambda_3, & \text{when } \alpha + \beta > 3. \end{cases} \quad (4.49)$$

We now want to find the correct semigroup leading from $osp(32/1)$ to the hidden superalgebra underlying $D = 11$ supergravity through our analytic method. Let us start from collecting the useful information coming from the starting algebra $osp(32/1)$. The generators

of $osp(32/1)$ are, with respect to the Lorentz subgroup $SO(1, 10) \subset osp(32/1)$, the following set of tensors (or spinors)

$$\{P_a, J_{ab}, Z_{a_1 \dots a_5}, Q_\alpha\}, \quad (4.50)$$

where J_{ab}, P_a, Q_α can be respectively interpreted as the Lorentz, translations and supersymmetry generators, and where $Z_{a_1 \dots a_5}$ is a 5-index skew-symmetric generator associated with the physical $A_{\mu\nu\rho}$ field appearing in $D = 11$ supergravity.

Now we have to take into account the information coming from the target superalgebra, that is to say the hidden superalgebra underlying the eleven-dimensional supergravity [38,39]. The generators of the mentioned superalgebra are given by the set

$$\{\tilde{P}_a, \tilde{J}_{ab}, \tilde{Z}_{ab}, \tilde{Z}_{a_1 \dots a_5}, \tilde{Q}_\alpha, \tilde{Q}'_\alpha\}, \quad (4.51)$$

where $\tilde{Z}_{ab}, \tilde{Z}_{a_1 \dots a_5}$ are two extra bosonic generators, and where \tilde{Q}' is an extra fermionic generator that controls the gauge symmetry of the theory and allows the closure of the algebra.

We perform the detailed calculations in Appendix D, while in the following we summarize our results.

At the end of the whole procedure, we are left with the following multiplication table:

	λ_0	λ_1	λ_2	λ_3	λ_4	
λ_0	λ_0	λ_1	λ_2	λ_3	λ_4	
λ_1	λ_1	λ_2	λ_3	λ_4	λ_4	
λ_2	λ_2	λ_3	λ_4	λ_4	λ_4	
λ_3	λ_3	λ_4	λ_4	λ_4	λ_4	
λ_4	λ_4	λ_4	λ_4	λ_4	λ_4	

(4.52)

which is the multiplication table describing the semigroup $S_E^{(3)}$, that, as it was also shown in [5], is exactly the semigroup leading, through a S -expansion procedure (0_S -resonant-reduction), from the $osp(32/1)$ algebra to the hidden superalgebra described in [38, 39]. Thus, we have shown that our analytic method immediately allows us to discover that these two superalgebras can be linked through a S -expansion procedure (0_S -resonant-reduction), involving the semigroup $S_E^{(3)}$.

We now make some consideration on the case in which

$$[\tilde{Q}, \tilde{P}_a] = 0, \quad (4.53)$$

that is one of the commutation relations the other superalgebra presented in [38]. In this case, from the relation

$$[\tilde{P}_a, \tilde{Q}] = [\lambda_e P_a, \lambda_c Q] = \lambda_e \lambda_c [P_a, Q] = 0 \quad \rightarrow \quad \lambda_e \lambda_c = \lambda_{0_S}, \quad (4.54)$$

we observe that we have to fix

$$\lambda_b = \lambda_e, \quad (4.55)$$

as we have done (see Appendix D) in the previous case, and also

$$\lambda_d = \lambda_{0_S}, \quad (4.56)$$

in order to have consistent multiplication rules. Thus, following the usual procedure, we can build the multiplication table of the set \tilde{S} , which in this case reads

	λ_0	λ_1	λ_2	λ_3	
λ_0	λ_0	λ_1	λ_2	λ_3	
λ_1	λ_1	λ_2	λ_3	λ_3	(4.57)
λ_2	λ_2	λ_3	λ_3	λ_3	
λ_3	λ_3	λ_3	λ_3	λ_3	

This is exactly the multiplication table describing the semigroup $S_E^{(2)}$, which satisfies the multiplication rules

$$\lambda_\alpha \lambda_\beta = \begin{cases} \lambda_{\alpha+\beta}, & \text{when } \alpha + \beta \leq 3, \\ \lambda_3, & \text{when } \alpha + \beta > 3. \end{cases} \quad (4.58)$$

In Ref. [5], the authors showed that $S_E^{(2)}$ is the semigroup allowing the S -expansion from $osp(32/1)$ to the M -algebra (the algebra of the M -theory). We have now shown that the same result is reproduced when we are dealing with a S -expansion (0_S -resonant-reduction) from $osp(32/1)$ to a particular subalgebra of the hidden superalgebra obtained in [38, 39] (that is to say, in the case in which \tilde{Q} and \tilde{P}_a commute).

Thus, a strong relation between the D'Auria-Fré superalgebra and the M -algebra is evident. Both of them, as it was shown in [5], can be reached with a S -expansion from $osp(32/1)$, respectively with the semigroup $S_E^{(2)}$ and $S_E^{(3)}$ (and this fact furnished us another corroboration of the analytic method developed in Section 3).

Furthermore, in our work we have interestingly shown that the particular subalgebra (where \tilde{P}_a and \tilde{Q} commute) of the hidden superalgebra underlying $D = 11$ supergravity is linked to $osp(32/1)$ by the semigroup $S_E^{(2)}$, which, in [5], was proven to link $osp(32/1)$ to the M -algebra through S -expansion.

Finally, we conclude our observations saying that, previously in [43] and later in [39], the authors also found a singular solution, which, in our notation, corresponds to consider the singular limit $\tilde{Q}' \rightarrow 0$ in the target superalgebra. In this case, the automorphism group of the FDA is enlarged to $Sp(32)$, and the whole procedure resembles an Inönü-Wigner contraction. Thus, we can clearly see the existence of a strong link between the mentioned superalgebras, given by the S -expansion (0_S -resonant-reduction) and the Inönü-Wigner contraction procedures. However, we will not treat the case involving the Inönü-Wigner contraction in our work, and we leave these considerations for the future.

5 Comments and possible developments

As we have previously said in the Introduction, a fundamental task to accomplish when dealing with the S -expansion is to find the appropriate semigroup linking two different

(super)algebras, but this procedure is not a trivial one, and usually requires a kind of “*trial and error*” process. In this paper, we have presented an *analytic method* able to give us the multiplication table(s) of the set(s) involved in an S -expansion process (with either resonance or 0_S -resonant-reduction) for reaching a target Lie (super)algebra from a starting one, after having properly chosen the partitions over subspaces of the considered (super)algebras. The analytic method described in this work gives a simple set of expressions to find the partitions over the set(s) involved in the process. Then, one can use the information coming from both the initial (super)algebra and the target one, in order to write the multiplication table(s) of the set(s). At the end of the procedure, one can check associativity by hand or with a simple computational algorithm (as we have done in this work), and thus end up with the complete multiplication table(s) of the semigroup(s) involved in the process. We have then given some interesting examples of application, starting from simple cases and ending with a particular case involving supersymmetric algebras. With these examples, we have reproduced well known results, which have already been presented in the literature, and we have also generalized some of them. We can thus conclude that our analytic method is reliable, and it can also be used in more complicated cases.

Future work can include the study of the particular cases in which the number of subspaces partitions of the target (super)algebra is *different* from the number of subspaces partition of the starting one, and the extension (and generalization) of our analytic method to the case of infinite algebras and semigroups. Furthermore, our analytic procedure can be used in future works for understanding the possible links that could exist between different (super)algebras (also in higher dimensional cases) that have not yet been analyzed in the S -expansion context.

5 Conclusions

In our first work [21] we perform a geometrical analysis of the S-expansion procedure. Here where discovered the local intrinsic changes that suffers the group manifold in concordance with the different multiplication tables of the semigroups, this changes are encoded in the M_K matrices, specifically in the effect that have this matrices on the metric tensor of the S-expanded Lie (Super)algebra.

This previous work was the cornerstone of the present due to the fact that the expressions constructed to find an analytical connection between two Lie (Super)algebras by means of the S-expansion procedure have founded its inspiration on the particular way in which the tensor metric of the Lie group manifold is modified by the (kind of) tensor metric of the semigroup and by the properties of the direct product \otimes . So now we have tried to carrier that new knowledge to the attempt in constructing an analytical and standard procedure that takes the axiomatic substance of the S-expansion and enlarge its mathematical structure to one that contains the *carrier elements* like the composed index Δ_A , the linear equation system (3.4) and the Identification Criterion. This objects are hooked to the principal properties of both algebras (starting/arrival) and meet in the missing part of the necessary information that would allow us to know if this two algebras share unique conditions that renders the arrival algebra the direct product of the starting one with a set S (Magma) under very interesting algebraic conditions

Through this analytical overview we have discovered the following:

- It's possible to construct an analytical tool (equation system (3.4)) that with a reduced amount of information coming from two Lie (Super)algebras give us immediately the answer about if this two algebras are linked by the S-expansion procedure. The answer is *yes* when the solution (that is always unique) is a set of numbers $\{\tilde{P}, \Delta_0, \dots, \Delta_{N-1}\}$ such that all of them belong to the naturals \mathbb{N} , otherwise there is no way to obtain one from another using the procedure.
- The information that lies in $\{\Delta_0, \dots, \Delta_{N-1}\}$ specifically, the unique identification between each partition element on $\tilde{S} = \sqcup S_{\Delta_A}$ and a subspace A in the original algebra can be carried to the S-expanded structure constants. This is very important because the one to one identification give us the closure relationship between the S_{Δ_A} under the set multiplication because the **need of respecting the one to one nature of the identification** (given by 3.4) **implies a necessary resonant behavior** between $S_{\Delta_A} \cdot S_{\Delta_B}$ and $[V_A, V_B]$ in this manner the resonance present in the S-expansion reborn in the form of a **necessary internal behavior in the partition $\tilde{S} = \sqcup S_{\Delta_A}$ due to the proportionality that must exist between the two algebras in study and its respective subspaces.**
- The index in each element of a set, for example the index a in $S_{1_A} = \{\lambda_a\}$ could be repeated (only) in other partition set, for example set $S_{3_B} = \{\lambda_b, \lambda_c, \lambda_d\}$ if the condition $\lambda_a = \lambda_b$ emerges from the use of the Identification Criterion. By other hand, the case in which $b = c$ will imply that it' produced a vector identification $T_1 = T_2$ in $\mathcal{G}_{S-\text{exp}}$ and in consequence its dimensionality reduces violating the (necessary) numeric value $\dim(\mathcal{G}_{S-\text{exp}}) = \sum_i \dim(\tilde{V}_i)$ established by means of (3.4)
- If the generators of the starting algebra \mathcal{G} satisfy the *theorem 3* then it's not necessary to require complete associativity to the set S , so in these cases would conserve just the magma algebraic properties.
- The final multiplication tables are total o partially defined depending on the of abelianity in the starting algebra \mathcal{G} due to the fact that a null commutator $[T_1, T_2] = \vec{0}$ will produce null commutators in $\mathcal{G}_{S-\text{exp}}$ independently of the S element that are multiplied by T_1 and T_2 (for example) so according to the multiplication table the bigger the degree of abelianity in the \mathcal{G} the more undefined it will be.

In terms of the analytical S-expansion method we have rendered some of its potulates to the level of natural consequences, like the resonant condition basing us on the idea of proportionality. Now the semigroup (or magma) definition and its resultant multiplication table is sited as the key that allow us to pass from one Lie algebra to another one by means of the direct product between the starting algebra \mathcal{G} and a set of finite and discrete sets \tilde{S} whose disjoint union satisfy at least the magma properties.

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"Look again at that dot. That's here. That's home. That's us. On it everyone you love, everyone you know, everyone you ever heard of, every human being who ever was, lived out their lives. The aggregate of our joy and suffering, thousands of confident religions, ideologies, and economic doctrines, every hunter and forager, every hero and coward, every creator and destroyer of civilization, every king and peasant, every young couple in love, every mother and father, hopeful child, inventor and explorer, every teacher of morals, every corrupt politician, every "superstar," every "supreme leader," every saint and sinner in the history of our species lived there-on a mote of dust suspended in a sunbeam".



Apendix

A Detailed calculations for moving from the Bianchi Type I algebra (BTI) to the Bianchi Type II algebra(BTII)

The BTI and BTII Lie algebras have two and three generators, respectively. The only commutator different from zero for the BTI algebra is

$$[X_1, X_2] = X_1, \quad (\text{A.1})$$

where X_1 and X_2 are the generators of the BTI algebra. For the BTII algebra we have

$$[Y_1, Y_2] = 0, \quad (\text{A.2})$$

$$[Y_1, Y_3] = 0, \quad (\text{A.3})$$

$$[Y_2, Y_3] = Y_1, \quad (\text{A.4})$$

where $Y_1, Y_2,$ and Y_3 are the generators of the BTII algebra.

Let us consider the following subspaces partition for the BTI algebra:

$$[V_0, V_0] \subset V_0, \quad (\text{A.5})$$

$$[V_0, V_1] \subset V_0 \oplus V_1, \quad (\text{A.6})$$

$$[V_1, V_1] \subset V_0, \quad (\text{A.7})$$

where we have set $V_0 = \{0\} \cup \{X_2\}$, and $V_1 = \{X_1\}$. Similarly, we can write the subspaces partition for the target BTII algebra:

$$[\tilde{V}_0, \tilde{V}_0] \subset \tilde{V}_0, \quad (\text{A.8})$$

$$[\tilde{V}_0, \tilde{V}_1] \subset \tilde{V}_0 \oplus \tilde{V}_1, \quad (\text{A.9})$$

$$[\tilde{V}_1, \tilde{V}_1] \subset \tilde{V}_0, \quad (\text{A.10})$$

where we have denoted with $\tilde{V}_A, A = 0, 1$, the subspaces related to the target algebra and where we have defined $\tilde{V}_0 = \{0\} \cup \{Y_3\}$, and $\tilde{V}_1 = \{Y_1, Y_2\}$. Let us observe that, in this way, we have the same partition structure both for the initial algebra and for the target one.

We now follow the steps described in the analytic procedure of Section 3, in order to obtain the possible abelian set(s) (with respect to the chosen partitions) leading from the BTI algebra to the BTII one.

First of all, we solve the system (3.5), that in this case reads

$$\begin{cases} 1 = 1 \cdot (\Delta_0), \\ 2 = 1 \cdot (\Delta_1), \\ \tilde{P} = \Delta_0 + \Delta_1 + 1, \end{cases} \quad (\text{A.11})$$

since

$$\dim(\tilde{V}_0) = 1, \quad \dim(V_0) = 1, \quad (\text{A.12})$$

$$\dim(\tilde{V}_1) = 2, \quad \dim(V_1) = 1, \quad (\text{A.13})$$

neglecting the zero element of the subspaces V_0 and \tilde{V}_0 . Here we have denoted, as usual, with $\Delta_A, A = 0, 1$, the cardinality of the subsets S_{Δ_A} associated with the subspace A , *i.e.* the number of elements in S_{Δ_A} . Solving the system above, we get the unique solution

$$\tilde{P} = 4, \quad \Delta_0 = 1, \quad \Delta_1 = 2. \quad (\text{A.14})$$

Now, since $\tilde{S} = \{S_{1_0}\} \sqcup \{S_{2_1}\} \cup \{\lambda_{0_S}\}$, where λ_{0_S} is the zero element of the set \tilde{S} , we can write the following partition structure over the set \tilde{S} :

$$\begin{aligned} S_{1_0} &= \{\lambda_a\}, \\ S_{2_1} &= \{\lambda_b, \lambda_c\}. \end{aligned} \quad (\text{A.15})$$

Here the index a, b, c identify general elements of the set \tilde{S} , and they are not running index. We do not yet identify them with numbers, because there still exists the possibility of having the same element in different subsets.

The next step consists in finding the multiplication rules between the elements of each subset in (A.15). Thus we write the adjoint representation of the BTI algebra with respect to the subspaces partition:

$$(C)_{0B}^C = \begin{pmatrix} (C)_{00}^0 & 0 \\ 0 & (C)_{01}^1 \end{pmatrix}, \quad (C)_{1B}^C = \begin{pmatrix} 0 & (C)_{10}^1 \\ (C)_{11}^0 & 0 \end{pmatrix}, \quad (\text{A.16})$$

where the index B, C can assume the values 0 or 1, labeling the different subspaces involved in the partition of the algebra. Thus, we are now able to write the relations (3.14), which, in this case, read

$$\begin{aligned} &[(S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0), (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0)] = \\ &= \left(K_{(1_0)(1_0)}^{(1_0)} (C)_{00}^0 \right) (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0), \\ &[(S_{2_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0)] = \\ &= \left(K_{(2_1)(1_0)}^{(2_1)} (C)_{10}^1 \right) (S_{2_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), \\ &[(S_{2_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), (S_{2_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1)] = \\ &= \left(K_{(2_1)(2_1)}^{(1_0)} (C)_{11}^0 \right) (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0). \end{aligned} \quad (\text{A.17})$$

These relations (which can also be rewritten in a simpler form, such as the one in (3.21)) give us a first view on the possibilities allowed by the multiplication table of the set \tilde{S} . In fact, we can now write

$$S_{1_0} \cdot S_{1_0} \subset S_{1_0} \cup \{\lambda_{0_S}\}, \quad (\text{A.18})$$

$$S_{2_1} \cdot S_{1_0} \subset S_{2_1} \cup \{\lambda_{0_S}\}, \quad (\text{A.19})$$

$$S_{2_1} \cdot S_{2_1} \subset S_{1_0} \cup \{\lambda_{0_S}\}, \quad (\text{A.20})$$

where we have taken into account the presence of the zero element λ_{0_S} of the set \tilde{S} . Thus, we are now able to write the possible multiplication rules between the elements of the set \tilde{S} , namely

$$\lambda_a \lambda_a = \lambda_{a,0_S}, \quad (\text{A.21})$$

$$\lambda_{b,c} \lambda_a = \lambda_{b,c,0_S}, \quad (\text{A.22})$$

$$\lambda_{b,c} \lambda_{b,c} = \lambda_{a,0_S}, \quad (\text{A.23})$$

where we have already taken into account the triviality of the multiplications rules

$$\lambda_{0_S} \lambda_{0_S} = \lambda_{0_S}, \quad (\text{A.24})$$

$$\lambda_{0_S} \lambda_{a,b,c} = \lambda_{0_S}. \quad (\text{A.25})$$

We have exhausted the information coming from the initial algebra, thus we now use the information coming from the target one, in order to build up the complete multiplication table of the set \tilde{S} .

We proceed by writing the relations between the S -expanded generators of the initial BTI algebra and the generators of the target BTII one, according to the usual S -expansion procedure described [5]. According to the identification criterion presented in Subsection 3.1, we can perform the identification

$$\lambda_a X_2 = Y_3 \quad (\text{A.26})$$

$$\lambda_b X_1 = Y_1 \quad (\text{A.27})$$

$$\lambda_c X_1 = Y_2. \quad (\text{A.28})$$

We now write the commutators of the target BTII algebra in terms of the commutators between the S -expanded, resonant-reduced generators of the BTI one:

$$\begin{aligned} [Y_2, Y_3] &= Y_1, \\ [\lambda_c X_1, \lambda_a X_2] &= \lambda_b X_1, \\ \lambda_c \lambda_a [X_1, X_2] &= \lambda_b X_1. \end{aligned} \quad (\text{A.29})$$

Since for the BTI algebra we have $[X_1, X_2] = X_1$, from equation (A.29) we obtain

$$\lambda_c \lambda_a = \lambda_b. \quad (\text{A.30})$$

This simple analysis can be performed in order to find the correct multiplication rules between the elements of the set \tilde{S} , thus we proceed in this way, computing the other commutators and factorizing the product between the elements of \tilde{S} , in order to end up with the complete multiplication table.

Let us observe that the commutator

$$[Y_1, Y_2] = 0 \quad (\text{A.31})$$

does not give us any further information about the multiplication rule between λ_b and λ_c , due to the fact that, when we write it in terms of the commutator between S -expanded generators and we factorize the product between the elements of \tilde{S} , we are left with $\lambda_b \lambda_c [X_1, X_1] = 0$, which reproduces a trivial identity, since $[X_1, X_1] = 0$ in the BTI algebra. On the other hand, from the study of the last commutator we have to consider, we get

$$\begin{aligned} [Y_1, Y_3] &= 0, \\ [\lambda_b X_1, \lambda_a X_2] &= 0, \\ \lambda_b \lambda_a [X_1, X_2] &= 0. \end{aligned} \quad (\text{A.32})$$

Since, from the initial BTI algebra, we know that $[X_1, X_2] = X_1 \neq 0$, from equation (A.32) we clearly see that the zero element λ_{0_S} is naturally involved in the procedure, and we can finally write

$$\lambda_b \lambda_a = \lambda_{0_S}. \quad (\text{A.33})$$

Summarizing, by following the identification criterion described in Subsection 3.1, we have obtained the multiplication rules

$$\lambda_c \lambda_a = \lambda_b, \quad (\text{A.34})$$

$$\lambda_b \lambda_a = \lambda_{0_S}. \quad (\text{A.35})$$

Let us notice that these multiplication rules are consistent with those previously obtained along the procedure, when we have exploited the information coming from the initial BTI algebra.

We are now able to write the following multiplication tables for the sets \tilde{S} 's involved in the procedure:

	λ_a	λ_b	λ_c	λ_{0_S}
λ_a	$\lambda_{a,0_S}$	λ_{0_S}	λ_b	λ_{0_S}
λ_b	λ_{0_S}	$\lambda_{a,0_S}$	$\lambda_{a,0_S}$	λ_{0_S}
λ_c	λ_b	$\lambda_{a,0_S}$	$\lambda_{a,0_S}$	λ_{0_S}
λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}

(A.36)

These are the multiplication tables of the possible sets \tilde{S} 's (with respect to the chosen partitions) involved in the S -expansion, 0_S -resonant-reduced procedure for moving from the BTI algebra to the BTII one.

B Detailed calculations for reaching $iso(2, 1)$, starting from $so(2, 2)$

Both $iso(2, 1)$ and $so(2, 2)$ have six generators. The commutation relations between the generators of the starting $so(2, 2)$ algebra are

$$[J_i, J_j] = \epsilon_{ijk} J^k, \quad (\text{B.1})$$

$$[J_i, P_j] = \epsilon_{ijk} P^k, \quad (\text{B.2})$$

$$[P_i, P_j] = \epsilon_{ijk} J^k, \quad (\text{B.3})$$

where $i, j, k, \dots = 1, 2, 3$, and the commutation relations between the generators of the target algebra $iso(2, 1)$ read

$$[\tilde{J}_i, \tilde{J}_j] = \epsilon_{ijk} \tilde{J}^k, \quad (\text{B.4})$$

$$[\tilde{J}_i, \tilde{P}_j] = \epsilon_{ijk} \tilde{P}^k, \quad (\text{B.5})$$

$$[\tilde{P}_i, \tilde{P}_j] = 0, \quad (\text{B.6})$$

where, again, $i, j, k, \dots = 1, 2, 3$.

We can write the following subspaces partition:

$$[V_0, V_0] \subset V_0, \quad (\text{B.7})$$

$$[V_0, V_1] \subset V_1, \quad (\text{B.8})$$

$$[V_1, V_1] \subset V_0 \quad (\text{B.9})$$

for $so(2, 2)$, where we have set $V_0 = \{J_i\}$ and $V_1 = \{P_i\}$, and

$$[\tilde{V}_0, \tilde{V}_0] \subset \tilde{V}_0, \quad (\text{B.10})$$

$$[\tilde{V}_0, \tilde{V}_1] \subset \tilde{V}_1, \quad (\text{B.11})$$

$$[\tilde{V}_1, \tilde{V}_1] \subset \tilde{V}_0 \quad (\text{B.12})$$

for $iso(2, 1)$, where, in analogy to what we have done for the initial algebra, $V_0 = \{0\} \oplus \{\tilde{J}_i\}$ and $V_1 = \{\tilde{P}_i\}$. Thus, we can now write:

$$dim(V_0) = 3, \quad (\text{B.13})$$

$$dim(V_1) = 3 \quad (\text{B.14})$$

for the $so(2, 2)$ algebra, and, similarly,

$$dim(\tilde{V}_0) = 3, \quad (\text{B.15})$$

$$dim(\tilde{V}_1) = 3 \quad (\text{B.16})$$

for the $iso(2, 2)$ one. Now we have all the information we need to know for proceeding. Thus, we move to the study of the system (3.5), which, in this case, reads

$$\begin{cases} 3 = 3 \cdot (\Delta_0), \\ 3 = 3 \cdot (\Delta_1), \\ \tilde{P} = \Delta_1 + \Delta_0 + 1. \end{cases} \quad (\text{B.17})$$

This system admits the unique solution

$$\tilde{P} = 3, \quad \Delta_0 = 1, \quad \Delta_1 = 1. \quad (\text{B.18})$$

Thus, we now know that the set $\tilde{S} = \{S_{1_0}\} \sqcup \{S_{1_1}\} \cup \{\lambda_{0_S}\}$, involved in the 0_S -resonant-reduction process to reach the algebra $iso(2, 1)$ starting from $so(2, 2)$, must have the following partition structure:

$$S_{1_0} = \{\lambda_a\}, \quad (\text{B.19})$$

$$S_{1_1} = \{\lambda_b\}. \quad (\text{B.20})$$

We can now write down the adjoint representation of $so(2, 2)$ with respect to the subspaces partition:

$$(C)_{0B}^C = \begin{pmatrix} (C)_{00}^0 & 0 \\ 0 & (C)_{01}^1 \end{pmatrix}, \quad (C)_{1B}^C = \begin{pmatrix} 0 & (C)_{10}^1 \\ (C)_{11}^0 & 0 \end{pmatrix}, \quad (\text{B.21})$$

where the index B, C can assume the values 0 or 1, labeling the different subspaces, and, subsequently, we are now able to write relations of the type (3.14), which, in this case, read

$$\begin{aligned} & [(S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0), (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0)] = \\ & = \left(K_{(1_0)(1_0)}^{(1_0)} (C)_{00}^0 \right) (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0), \\ & [(S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0)] = \\ & = \left(K_{(1_1)(1_0)}^{(1_1)} (C)_{10}^1 \right) (S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), \\ & [(S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), (S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1)] = \\ & = \left(K_{(1_1)(1_1)}^{(1_0)} (C)_{11}^0 \right) (S_{1_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0). \end{aligned} \quad (\text{B.22})$$

These relations (which can also be rewritten in a simpler form of the type (3.21)) lead us to a first view on the multiplication rules between the subsets of the set \tilde{S} , namely

$$S_{1_0} \cdot S_{1_0} \subset S_{1_0} \cup \{\lambda_{0_S}\}, \quad (\text{B.23})$$

$$S_{1_1} \cdot S_{1_0} \subset S_{1_1} \cup \{\lambda_{0_S}\}, \quad (\text{B.24})$$

$$S_{1_1} \cdot S_{1_1} \subset S_{1_0} \cup \{\lambda_{0_S}\}, \quad (\text{B.25})$$

where we have taken into account the presence of the zero element λ_{0_S} of the set \tilde{S} .

In terms of the elements of the subsets, we can now write

$$\lambda_a \lambda_a = \lambda_{a,0_S}, \quad (\text{B.26})$$

$$\lambda_b \lambda_a = \lambda_{b,0_S}, \quad (\text{B.27})$$

$$\lambda_b \lambda_b = \lambda_{a,0_S}, \quad (\text{B.28})$$

where we have already taken into account the triviality of the multiplications rules

$$\lambda_{0_S} \lambda_{0_S} = \lambda_{0_S}, \quad (\text{B.29})$$

$$\lambda_{0_S} \lambda_{a,b} = \lambda_{0_S}. \quad (\text{B.30})$$

Then, by exploiting the information coming from the target algebra, we will be able to fix the degeneracy present in the above multiplication rules.

To this aim, let us perform the following associations between the S -expanded generators of the starting algebra and the generators of the target one (according to the identification criterion described in Subsection 3.1):

$$\lambda_a J_i = \tilde{J}_i, \quad (\text{B.31})$$

$$\lambda_b P_i = \tilde{P}_i. \quad (\text{B.32})$$

Now we can write, according to the S -expansion procedure [5], the commutators of the target $iso(2, 1)$ algebra in terms of the commutators between the S -expanded generators of the $so(2, 2)$ one:

$$\begin{aligned} [\tilde{J}_i, \tilde{J}_j] &\propto \tilde{J}_k, \\ [\lambda_a J_i, \lambda_a J_j] &\propto \lambda_a J_k, \\ \lambda_a \lambda_a [J_i, J_j] &\propto \lambda_a J_k. \end{aligned} \tag{B.33}$$

Since $[J_i, J_j] \propto J_k$, equation (B.33) tells us that

$$\lambda_a \lambda_a = \lambda_a. \tag{B.34}$$

Similarly, since $[J_i, P_j] \propto P_k$, the analysis of

$$\begin{aligned} [\tilde{J}_i, \tilde{P}_j] &\propto \tilde{P}_k, \\ [\lambda_a J_i, \lambda_b P_j] &\propto \lambda_b P_k, \\ \lambda_a \lambda_b [J_i, P_j] &\propto \lambda_b P_k \end{aligned} \tag{B.35}$$

gives us

$$\lambda_a \lambda_b = \lambda_b. \tag{B.36}$$

Finally, from

$$\begin{aligned} [\tilde{P}_i, \tilde{P}_j] &= 0, \\ [\lambda_b P_i, \lambda_b P_j] &= 0, \\ \lambda_b \lambda_b [P_i, P_j] &= 0, \end{aligned} \tag{B.37}$$

we can write

$$\lambda_b \lambda_b = \lambda_{0_S}, \tag{B.38}$$

since $[P_i, P_j] \propto J_k \neq 0$.

Summarizing, we are left with the multiplication rules

$$\lambda_a \lambda_a = \lambda_a, \tag{B.39}$$

$$\lambda_a \lambda_b = \lambda_b, \tag{B.40}$$

$$\lambda_b \lambda_b = \lambda_{0_S}. \tag{B.41}$$

In this way, we have completely fixed the degeneracy appearing in the multiplication rules between the elements of the set \tilde{S} and we are finally able to write the multiplication table of the set \tilde{S} , which reads

	λ_a	λ_b	λ_{0_S}	
λ_a	λ_a	λ_b	λ_{0_S}	
λ_b	λ_b	λ_{0_S}	λ_{0_S}	
λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	

(B.42)

Here we have completed the multiplication table with the zero element λ_{0_S} , by exploiting the definition $\lambda_{0_S}\lambda_{a,b} = \lambda_{0_S}$.

After having performed the identification

$$\lambda_a \leftrightarrow \lambda_0, \quad (\text{B.43})$$

$$\lambda_b \leftrightarrow \lambda_1, \quad (\text{B.44})$$

$$\lambda_{0_S} \leftrightarrow \lambda_2, \quad (\text{B.45})$$

we can write the above multiplication table as follow:

	λ_0	λ_1	λ_2	
λ_0	λ_0	λ_1	λ_2	
λ_1	λ_1	λ_2	λ_2	
λ_2	λ_2	λ_2	λ_2	

(B.46)

Table (B.46) is an abelian and associative one (the check for associativity can be performed either by hand or using a simple computational algorithm), and thus it describes the semi-group leading from the $so(2,2)$ algebra to the $iso(2,1)$ one (with respect to the partitions over subspaces that we have chosen).

C Detailed calculations for moving from the Anti-de Sitter (AdS) algebra to the Maxwell algebra

The AdS Lie algebra has ten generators, while the Maxwell algebra (\mathcal{M}) counts sixteen generators. The generators of the AdS algebra are $\{J_{ab}, P_a\}$, and they satisfy the commutation relations

$$[J_{ab}, J_{cd}] = \eta_{bc}J_{cd} - \eta_{ac}J_{bd} - \eta_{bd}J_{ac} + \eta_{ad}J_{bc}, \quad (\text{C.1})$$

$$[J_{ab}, P_c] = \eta_{bc}P_a - \eta_{ac}P_b, \quad (\text{C.2})$$

$$[P_a, P_b] = J_{ab}. \quad (\text{C.3})$$

The generators of the Maxwell algebra \mathcal{M} are $\{\tilde{J}_{ab}, \tilde{P}_a, \tilde{Z}_{ab}\}$, and they satisfy the following commutation relations:

$$[\tilde{J}_{ab}, \tilde{Z}_{cd}] = \eta_{bc}\tilde{Z}_{cd} - \eta_{ac}\tilde{Z}_{bd} - \eta_{bd}\tilde{Z}_{ac} + \eta_{ad}\tilde{Z}_{bc}, \quad (\text{C.4})$$

$$[\tilde{Z}_{ab}, \tilde{P}_a] = 0, \quad (\text{C.5})$$

$$[\tilde{Z}_{ab}, \tilde{Z}_{cd}] = 0, \quad (\text{C.6})$$

$$[\tilde{J}_{ab}, \tilde{J}_{cd}] = \eta_{bc}\tilde{J}_{cd} - \eta_{ac}\tilde{J}_{bd} - \eta_{bd}\tilde{J}_{ac} + \eta_{ad}\tilde{J}_{bc}, \quad (\text{C.7})$$

$$[\tilde{J}_{ab}, \tilde{P}_c] = \eta_{bc}\tilde{P}_a - \eta_{ac}\tilde{P}_b, \quad (\text{C.8})$$

$$[\tilde{P}_a, \tilde{P}_b] = \tilde{Z}_{ab}. \quad (\text{C.9})$$

The subspace structure of the *AdS* Lie algebra can be written as

$$[V_0, V_0] \subset V_0, \quad (\text{C.10})$$

$$[V_0, V_1] \subset V_1, \quad (\text{C.11})$$

$$[V_1, V_1] \subset V_0, \quad (\text{C.12})$$

where $V_0 = \{J_{ab}\}$ and $V_1 = \{P_a\}$.

The subspace structure of the Maxwell algebra \mathcal{M} , in analogy to what we have done for the *AdS* algebra, may be written as

$$[\tilde{V}_0, \tilde{V}_0] \subset \tilde{V}_0, \quad (\text{C.13})$$

$$[\tilde{V}_0, \tilde{V}_1] \subset \tilde{V}_0 \oplus \tilde{V}_1, \quad (\text{C.14})$$

$$[\tilde{V}_1, \tilde{V}_1] \subset \tilde{V}_0, \quad (\text{C.15})$$

where $\tilde{V}_0 = \{0\} \cup \{\tilde{J}_{ab}, \tilde{Z}_{ab}\}$ and $\tilde{V}_1 = \{\tilde{P}_a\}$. Thus, we have

$$\dim(V_0) = 6, \quad (\text{C.16})$$

$$\dim(V_1) = 4 \quad (\text{C.17})$$

for the *AdS* algebra, and

$$\dim(\tilde{V}_0) = 12, \quad (\text{C.18})$$

$$\dim(\tilde{V}_1) = 4 \quad (\text{C.19})$$

for the Maxwell one.

Now, we can solve the usual system (3.5), which in this case reads

$$\begin{cases} 12 = 6 \cdot (\Delta_0), \\ 4 = 4 \cdot (\Delta_1), \\ \tilde{P} = \Delta_0 + \Delta_1 + 1. \end{cases} \quad (\text{C.20})$$

This system has the unique solution

$$\tilde{P} = 4, \quad \Delta_0 = 2, \quad \Delta_1 = 1. \quad (\text{C.21})$$

Thus, we now know that the set $\tilde{S} = \{S_{2_0}\} \sqcup \{S_{1_1}\} \cup \{\lambda_{0_S}\}$, involved in the 0_S -resonant-reduction procedure to reach the Maxwell algebra \mathcal{M} starting from the *AdS* Lie one, must have the following partition structure:

$$S_{2_0} = \{\lambda_a, \lambda_b\}, \quad (\text{C.22})$$

$$S_{1_1} = \{\lambda_c\}. \quad (\text{C.23})$$

By following the usual method (see Section 3), now we write down the adjoint representation of the *AdS* algebra with respect to the subspaces partition, namely

$$(C)_{0B}^C = \begin{pmatrix} (C)_{00}^0 & 0 \\ 0 & (C)_{01}^1 \end{pmatrix}, \quad (C)_{1B}^C = \begin{pmatrix} 0 & (C)_{10}^1 \\ (C)_{11}^0 & 0 \end{pmatrix}, \quad (\text{C.24})$$

where the index B, C can take the values 0 or 1, labeling the different subspaces.

Consequently, we can write relations (3.14) as follows:

$$\begin{aligned} & [(S_{2_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0), (S_{2_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0)] = \\ & = \left(K_{(2_0)(2_0)}^{(2_0)} (C)_{00}^0 \right) (S_{2_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0), \\ & [(S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), (S_{2_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0)] = \\ & = \left(K_{(1_1)(2_0)}^{(1_1)} (C)_{10}^1 \right) (S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), \\ & [(S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1), (S_{1_1} \otimes V_1) \oplus (\{\lambda_{0_S}\} \otimes V_1)] = \\ & = \left(K_{(1_1)(1_1)}^{(2_0)} (C)_{11}^0 \right) (S_{2_0} \otimes V_0) \oplus (\{\lambda_{0_S}\} \otimes V_0). \end{aligned} \quad (\text{C.25})$$

These relations (which can be rewritten in the simpler form described in (3.21)) tell us the composition rules of the subsets of the set \tilde{S} , which read

$$S_{2_0} \cdot S_{2_0} \subset S_{2_0} \cup \{\lambda_{0_S}\}, \quad (\text{C.26})$$

$$S_{2_0} \cdot S_{1_1} \subset S_{1_1} \cup \{\lambda_{0_S}\}, \quad (\text{C.27})$$

$$S_{1_1} \cdot S_{1_1} \subset S_{2_0} \cup \{\lambda_{0_S}\}, \quad (\text{C.28})$$

where we have explicitly taken into account the presence of the zero element λ_{0_S} .

Thus, we can write the following multiplication rules for the elements of the set \tilde{S} :

$$\lambda_{a,b} \lambda_{a,b} = \lambda_{a,b,0_S}, \quad (\text{C.29})$$

$$\lambda_{a,b} \lambda_c = \lambda_{c,0_S}, \quad (\text{C.30})$$

$$\lambda_c \lambda_c = \lambda_{a,b,0_S}, \quad (\text{C.31})$$

where we have already taken into account the triviality of the multiplications rules

$$\lambda_{0_S} \lambda_{0_S} = \lambda_{0_S}, \quad (\text{C.32})$$

$$\lambda_{0_S} \lambda_{a,b,c} = \lambda_{0_S}. \quad (\text{C.33})$$

Then, by exploiting the information coming from the target algebra, we will be able to completely fix the degeneracy still appearing in the above multiplication rules.

Thus, we write the generators of the Maxwell algebra \mathcal{M} in terms of the S -expanded generators of the *AdS* Lie algebra, performing the following identification (according to the identification criterion of Subsection 3.1):

$$\lambda_a J_{ab} = \tilde{J}_{ab}, \quad (\text{C.34})$$

$$\lambda_b J_{ab} = \tilde{Z}_{ab}, \quad (\text{C.35})$$

$$\lambda_c P_a = \tilde{P}_a. \quad (\text{C.36})$$

Consequently, according to the S -expansion procedure described in [5], we can write the commutators of the target Maxwell algebra in terms of the commutators between the S -expanded generators of the AdS one, taking into account the commutation relations of the initial AdS Lie algebra (in the following, we will neglect, for simplicity, the index labeling the generators, since we just need to exploit the commutators structure).

We get

$$\begin{aligned} [\tilde{J}, \tilde{J}] &\propto \tilde{J}, \\ [\lambda_a J, \lambda_a J] &\propto \lambda_a J, \\ \lambda_a \lambda_a [J, J] &\propto \lambda_a J \quad \Rightarrow \quad \lambda_a \lambda_a = \lambda_a; \end{aligned} \tag{C.37}$$

$$\begin{aligned} [\tilde{J}, \tilde{P}] &\propto \tilde{P}, \\ [\lambda_a J, \lambda_c P] &\propto \lambda_c P, \\ \lambda_a \lambda_c [J, P] &\propto \lambda_c P \quad \Rightarrow \quad \lambda_a \lambda_c = \lambda_c; \end{aligned} \tag{C.38}$$

$$\begin{aligned} [\tilde{J}, \tilde{Z}] &\propto \tilde{Z}, \\ [\lambda_a J, \lambda_b J] &\propto \lambda_b J, \\ \lambda_a \lambda_b [J, J] &\propto \lambda_b J \quad \Rightarrow \quad \lambda_a \lambda_b = \lambda_b; \end{aligned} \tag{C.39}$$

$$\begin{aligned} [\tilde{P}, \tilde{P}] &\propto \tilde{P}, \\ [\lambda_c P, \lambda_c P] &\propto \lambda_c P, \\ \lambda_c \lambda_c [P, P] &\propto \lambda_c P \quad \Rightarrow \quad \lambda_c \lambda_c = \lambda_c; \end{aligned} \tag{C.40}$$

$$\begin{aligned} [\tilde{Z}, \tilde{P}] &= 0, \\ [\lambda_b J, \lambda_c P] &= 0, \\ \lambda_b \lambda_c [J, P] &= 0 \quad \Rightarrow \quad \lambda_b \lambda_c = \lambda_{0_S}, \end{aligned} \tag{C.41}$$

since $[J, P] = P \neq 0$;

$$\begin{aligned} [\tilde{Z}, \tilde{Z}] &= 0, \\ [\lambda_b J, \lambda_b J] &= 0, \\ \lambda_b \lambda_b [J, J] &= 0 \quad \Rightarrow \quad \lambda_b \lambda_b = \lambda_{0_S}, \end{aligned} \tag{C.42}$$

since $[J, J] = J \neq 0$. From the above relations, we can write the multiplication table

	λ_a	λ_b	λ_c	λ_{0_S}	
λ_a	λ_a	λ_b	λ_c	λ_{0_S}	
λ_b	λ_b	λ_{0_S}	λ_{0_S}	λ_{0_S}	
λ_c	λ_c	λ_{0_S}	λ_c	λ_{0_S}	
λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	

(C.43)

in which we can see that all the degeneracy has been fixed. Then, after having performed the identification

$$\lambda_a \leftrightarrow \lambda_0, \quad \lambda_b \leftrightarrow \lambda_2, \quad \lambda_c \leftrightarrow \lambda_1, \quad \lambda_{0_S} \leftrightarrow \lambda_2, \quad (\text{C.44})$$

we can write the following multiplication table (where the elements of the set \tilde{S} are written in the usual order):

	λ_0	λ_1	λ_2	λ_3	
λ_0	λ_0	λ_1	λ_2	λ_3	
λ_1	λ_1	λ_2	λ_3	λ_3	
λ_2	λ_2	λ_3	λ_3	λ_3	
λ_3	λ_3	λ_3	λ_3	λ_3	

(C.45)

Table (C.45) represents an abelian, commutative and associative semigroup, named $S_E^{(2)}$. As said in [22–24], $S_E^{(2)}$ is the semigroup involved in the S -expansion (0_S -resonant-reduction) procedure performed in order to reach the Maxwell algebra \mathcal{M} starting from the AdS Lie algebra, and we have reproduced this result with our analytic method.

D Detailed calculations for reaching the hidden superalgebra underlying $D=11$ supergravity, starting from the supersymmetric Lie algebra $osp(32/1)$

In the following, we display the detailed calculations for moving from the supersymmetric Lie algebra $osp(32/1)$ to the hidden superalgebra underlying $D = 11$ supergravity, through a 0_S -resonant-reduction procedure, and we show how to find the set(s) involved in the process, once the partitions over subspaces for both the considered superalgebras have been properly chosen.

The generators of $osp(32/1)$ are

$$\{P_a, J_{ab}, Z_{a_1 \dots a_5}, Q_\alpha\}. \quad (\text{D.1})$$

The commutations relation between these generators can be written as

$$\begin{aligned}
[P_a, P_b] &= J_{ab}, \\
[J^{ab}, P_c] &= \delta_{ec}^{ab} P^e, \\
[J^{ab}, J_{cd}] &= \delta_{ecd}^{abf} J_f^e, \\
[P_a, Z_{c_1 \dots c_5}] &= -\frac{1}{5!} \epsilon_{ab_1 \dots b_5 c_1 \dots c_5} Z^{c_1 \dots c_5}, \\
[J^{ab}, Z_{c_1 \dots c_5}] &= \frac{1}{4!} \delta_{dc_1 \dots c_5}^{abe_1 \dots e_4} Z_{e_1 \dots e_4}^d, \\
[Z^{a_1 \dots a_5}, Z_{b_1 \dots b_5}] &= \eta^{[a_1 \dots a_5][c_1 \dots c_5]} \epsilon_{c_1 \dots c_5 b_1 \dots b_5 e} P^e + \delta_{db_1 \dots b_5}^{a_1 \dots a_5 e} J_e^d + \\
&\quad - \frac{1}{3!3!5!} \epsilon_{c_1 \dots c_{11}} \delta_{d_1 d_2 d_3 b_1 \dots b_5}^{a_1 \dots e_5 c_4 c_5 c_6} \eta^{[c_1 c_2 c_3][d_1 d_2 d_3]} Z^{c_7 \dots c_{11}}, \\
[P_a, Q] &= -\frac{1}{2} \Gamma_a Q, \\
[J_{ab}, Q] &= -\frac{1}{2} \Gamma_{ab} Q, \\
[Z_{abcde}, Q] &= -\frac{1}{2} \Gamma_{abcde} Q, \\
\{Q^\rho, Q^\sigma\} &= -\frac{1}{2^3} \left[(\Gamma^a C^{-1})^{\rho\sigma} P_a - \frac{1}{2} (\Gamma^{ab} C^{-1})^{\rho\sigma} J_{ab} \right] + \\
&\quad - \frac{1}{2^3} \left[\frac{1}{5!} (\Gamma^{abcde} C^{-1})^{\rho\sigma} Z_{abcde} \right], \tag{D.2}
\end{aligned}$$

where $C_{\rho\sigma}$ is the charge conjugation matrix and $\Gamma_a, \Gamma_{ab}, \Gamma_{abcde}$ are the Dirac matrices in eleven dimensions. Let us perform the following subspaces partition for the $osp(32/1)$ algebra:

$$[V_0, V_0] \subset V_0, \tag{D.3}$$

$$[V_0, V_1] \subset V_1, \tag{D.4}$$

$$[V_0, V_2] \subset V_2, \tag{D.5}$$

$$[V_1, V_1] \subset V_0 \oplus V_2, \tag{D.6}$$

$$[V_1, V_2] \subset V_1, \tag{D.7}$$

$$[V_2, V_2] \subset V_0 \oplus V_2, \tag{D.8}$$

where we have set $V_0 = \{J_{ab}\}$, $V_1 = \{Q_\alpha\}$, and $V_2 = \{P_a, Z_{a_1 \dots a_5}\}$. Thus, the dimensions of the internal decomposition of $osp(32/1)$ read

$$\dim(V_0) = \underbrace{55}_{J_{ab}}, \tag{D.9}$$

$$\dim(V_1) = \underbrace{32}_{Q_\alpha}, \tag{D.10}$$

$$\dim(V_2) = \underbrace{11}_{P_a} + \underbrace{462}_{Z_{a_1 \dots a_5}} = 473. \tag{D.11}$$

The generators of the superalgebra underlying $D = 11$ supergravity are given by the set

$$\{\tilde{P}_a, \tilde{J}_{ab}, \tilde{Z}_{ab}, \tilde{Z}_{a_1\dots a_5}, \tilde{Q}_\alpha, \tilde{Q}'_\alpha\}. \quad (\text{D.12})$$

These generators satisfy the following commutation relations:

$$\begin{aligned} \{\tilde{Q}, \tilde{Q}\} &= -\left(i\Gamma^a \tilde{P}_a + \frac{1}{2}\Gamma^{ab} \tilde{Z}_{ab} + \frac{i}{5!}\Gamma^{a_1\dots a_5} \tilde{Z}_{a_1\dots a_5}\right), \\ \{\tilde{Q}', \tilde{Q}'\} &= 0, \\ \{\tilde{Q}, \tilde{Q}'\} &= 0, \\ [\tilde{Q}, \tilde{P}_a] &= -2i \binom{5}{0} \Gamma_a \tilde{Q}', \\ [\tilde{Q}, \tilde{Z}^{ab}] &= -4\Gamma^{ab} \tilde{Q}', \\ [\tilde{Q}, \tilde{Z}^{a_1\dots a_5}] &= -2(5!)i \left(\frac{1}{\frac{48}{1}}\right) \Gamma^{a_1\dots a_5} \tilde{Q}', \\ [\tilde{J}_{ab}, \tilde{Z}^{cd}] &= -8\delta_{[a}^{[c} \tilde{Z}_{b]}^{d]}, \\ [\tilde{J}_{ab}, \tilde{Z}^{c_1\dots c_5}] &= -20\delta_{[a}^{[c_1} \tilde{Z}_{b]}^{c_2\dots c_5]}, \\ [\tilde{J}_{ab}, \tilde{Q}] &= -\Gamma_{ab} \tilde{Q}, \\ [\tilde{J}_{ab}, \tilde{Q}'] &= -\Gamma_{ab} \tilde{Q}', \\ [\tilde{P}_a, \tilde{Q}'] &= [\tilde{Z}_{ab}, \tilde{Q}'] = [\tilde{Z}_{ab}, \tilde{Q}'] = [\tilde{Z}_{a_1\dots a_5}, \tilde{Q}'] = [\tilde{P}_a, \tilde{P}_b] = 0, \\ [\tilde{J}^{ab}, \tilde{P}_c] &= \delta_{ec}^{ab} \tilde{P}^e, \\ [\tilde{J}^{ab}, \tilde{J}_{cd}] &= \delta_{ecd}^{abf} \tilde{J}_f, \\ [\tilde{Z}_{ab}, \tilde{Z}_{bc}] &= [\tilde{Z}_{ab}, \tilde{Z}_{a_1\dots a_5}] = [\tilde{Z}_{ab}, \tilde{P}_c] = 0, \end{aligned} \quad (\text{D.13})$$

where the free parameter E_2 appearing in Ref. [39] has been consistently fixed to the value 1 (this is due to the possibility of fixing the normalization of the differential form associated with the extra fermionic generator \tilde{Q}').

We observe that the above algebra actually describes two superalgebras, due to the degeneracy appearing in the commutation relation (D.13), from which we clearly see that the generators \tilde{Q} and \tilde{P}_a can also commute. In the following, we will discuss the S -expansion, 0_S -resonant-reduced procedure for both these superalgebras.

Let us also observe that, in the description of the hidden superalgebra, the coefficients are written following the notation and conventions presented in Ref.s [38, 39], while, when considering the supersymmetric $osp(32/1)$ Lie algebra, we have adopted the notation presented in Ref. [5]. However, the coefficients appearing in the mentioned algebras are not relevant to our discussion, since we just need to know the *structure* of the algebras for applying our analytic method.

We can thus proceed, giving the internal decomposition of the target superalgebra (we first consider the case in which $[\tilde{Q}, \tilde{P}_a] \neq 0$). For the target superalgebra underlying $D = 11$ supergravity, we can write

$$\dim(\tilde{V}_0) = \underbrace{110}_{\tilde{J}_{ab}, \tilde{Z}_{ab}}, \quad (\text{D.14})$$

$$\dim(\tilde{V}_1) = \underbrace{64}_{\tilde{Q}_\alpha, \tilde{Q}'_\alpha}, \quad (\text{D.15})$$

$$\dim(\tilde{V}_2) = \underbrace{11}_{\tilde{P}_a} + \underbrace{462}_{\tilde{Z}_{a_1 \dots a_5}} = 473. \quad (\text{D.16})$$

where we have clearly set $\tilde{V}_0 = \{0\} \cup \{\tilde{J}_{ab}, \tilde{Z}_{ab}\}$, $\tilde{V}_1 = \{\tilde{Q}, \tilde{Q}'\}$, and $\tilde{V}_2 = \{\tilde{P}_a, \tilde{Z}_{a_1 \dots a_5}\}$. The subspaces partition for the target superalgebra satisfies the following relations

$$[\tilde{V}_0, \tilde{V}_0] \subset \tilde{V}_0, \quad (\text{D.17})$$

$$[\tilde{V}_0, \tilde{V}_1] \subset \tilde{V}_0 \oplus \tilde{V}_1, \quad (\text{D.18})$$

$$[\tilde{V}_0, \tilde{V}_2] \subset \tilde{V}_0 \oplus \tilde{V}_2, \quad (\text{D.19})$$

$$[\tilde{V}_1, \tilde{V}_1] \subset \tilde{V}_0 \oplus \tilde{V}_2, \quad (\text{D.20})$$

$$[\tilde{V}_1, \tilde{V}_2] \subset \tilde{V}_0 \oplus \tilde{V}_1, \quad (\text{D.21})$$

$$[\tilde{V}_2, \tilde{V}_2] \subset \tilde{V}_0 \oplus \tilde{V}_2, \quad (\text{D.22})$$

analogously to what we have done for $osp(32/1)$. We can now move to the study of the usual system (3.5), which, in this case, reads

$$\begin{cases} 110 = 55(\tilde{P} - 1 - \Delta_1 - \Delta_2), \\ 64 = 32(\tilde{P} - 1 - \Delta_0 - \Delta_2), \\ 473 = 473(\tilde{P} - 1 - \Delta_0 - \Delta_1), \\ \tilde{P} = \Delta_0 + \Delta_1 + \Delta_2 + 1, \end{cases} \quad (\text{D.23})$$

where $\Delta_0, \Delta_1, \Delta_2$ respectively denote the cardinality of the subsets related to the subspaces V_0, V_1 , and V_2 . This system admits the unique solution

$$\tilde{P} = 6, \quad \Delta_0 = 2, \quad \Delta_1 = 2, \quad \Delta_2 = 1. \quad (\text{D.24})$$

Thus, we are now able to write the following decomposition over the set \tilde{S} involved in the process:

$$S_{2_0} = \{\lambda_a, \lambda_b\}, \quad (\text{D.25})$$

$$S_{2_1} = \{\lambda_c, \lambda_d\}, \quad (\text{D.26})$$

$$S_{1_2} = \{\lambda_e\}. \quad (\text{D.27})$$

Now, we build up the adjoint representation with respect to the subspaces partition of the starting $osp(32/1)$ algebra, namely

$$(C)_{0B}^C = \begin{pmatrix} (C)_{00}^0 & 0 & 0 \\ 0 & (C)_{01}^1 & 0 \\ 0 & 0 & (C)_{02}^2 \end{pmatrix}, \quad (C)_{1B}^C = \begin{pmatrix} 0 & (C)_{10}^1 & 0 \\ (C)_{11}^0 & 0 & (C)_{11}^2 \\ 0 & (C)_{12}^1 & 0 \end{pmatrix},$$

$$(C)_{2B}^C = \begin{pmatrix} 0 & 0 & (C)_{20}^2 \\ 0 & (C)_{21}^1 & 0 \\ (C)_{22}^0 & 0 & (C)_{21}^2 \end{pmatrix}.$$

Thus, one can now write the usual relations (3.14) (or their simpler form, given by (3.21)) for the case under analysis, and find the following product structure for the partitions over the set \tilde{S}

$$S_{2_0} \cdot S_{2_0} \subset S_{2_0} \cup \{\lambda_{0_S}\}, \quad (D.28)$$

$$S_{2_0} \cdot S_{2_1} \subset S_{2_1} \cup \{\lambda_{0_S}\}, \quad (D.29)$$

$$S_{2_0} \cdot S_{1_2} \subset S_{1_2} \cup \{\lambda_{0_S}\}, \quad (D.30)$$

$$S_{2_1} \cdot S_{2_1} \subset (S_{2_0} \cap S_{1_2}) \cup \{\lambda_{0_S}\}, \quad (D.31)$$

$$S_{2_1} \cdot S_{1_2} \subset S_{1_2} \cup \{\lambda_{0_S}\}, \quad (D.32)$$

$$S_{1_2} \cdot S_{1_2} \subset (S_{2_0} \cap S_{1_2}) \cup \{\lambda_{0_S}\}, \quad (D.33)$$

where we have explicitly taken into account the presence of the zero element λ_{0_S} . This allows to reach the multiplication rules

$$\lambda_{a,b}\lambda_{a,b} = \lambda_{a,b,0_S}, \quad (D.34)$$

$$\lambda_{a,b}\lambda_{c,d} = \lambda_{c,d,0_S}, \quad (D.35)$$

$$\lambda_{a,b}\lambda_e = \lambda_{e,0_S}, \quad (D.36)$$

$$\lambda_{b,c}\lambda_{b,c} = \lambda_{a,b,e,0_S}, \quad (D.37)$$

$$\lambda_{b,c}\lambda_e = \lambda_{e,0_S}, \quad (D.38)$$

$$\lambda_e\lambda_e = \lambda_{a,b,e,0_S}, \quad (D.39)$$

where we have already taken into account the triviality of the multiplications rules

$$\lambda_{0_S}\lambda_{0_S} = \lambda_{0_S}, \quad (D.40)$$

$$\lambda_{0_S}\lambda_{a,b,c,d,e} = \lambda_{0_S}. \quad (D.41)$$

We can now fix the degeneracy appearing in the above multiplication rules, by analyzing the information coming from the target superalgebra. According to the usual S -expansion procedure (see Ref. [5]), we have to write the commutation relations between the generators of the target superalgebra in terms of the commutation relations between the generators of the S -expanded $osp(32/1)$. After having performed the identification (according to the identification criterion presented in Subsection 3.1)

$$\lambda_a J_{ab} = \tilde{J}_{ab}, \quad \lambda_b J_{ab} = \tilde{Z}_{ab}, \quad \lambda_c Q = \tilde{Q}, \quad \lambda_d Q = \tilde{Q}', \quad \lambda_e P_a = \tilde{P}_a, \quad \lambda_e Z_{a_1 \dots a_5} = \tilde{Z}_{a_1 \dots a_5}, \quad (D.42)$$

we are able to write the commutation relations of the superalgebra underlying $D = 11$ supergravity in terms of the commutation relations of the S -expanded generators of $osp(32/1)$. In the following, we will just consider the structure of the commutation relations, since the explicit values of the coefficients are not relevant to our analysis. For performing this calculation, we consider the case in which $[\tilde{Q}, \tilde{P}_a] \neq 0$.

Thus, taking into account the commutation relations for the initial algebra $osp(32/1)$, we have:

$$\{\tilde{Q}', \tilde{Q}'\} = \{\lambda_d Q, \lambda_d Q\} = \lambda_d \lambda_d \{Q, Q\} = 0 \quad \rightarrow \quad \lambda_d \lambda_d = \lambda_{0_S}, \quad (\text{D.43})$$

$$\{\tilde{Q}, \tilde{Q}'\} = \{\lambda_c Q, \lambda_d Q\} = \lambda_c \lambda_d \{Q, Q\} = 0 \quad \rightarrow \quad \lambda_c \lambda_d = \lambda_{0_S}, \quad (\text{D.44})$$

$$[\tilde{P}_a, \tilde{P}_b] = [\lambda_e P_a, \lambda_e P_b] = \lambda_e \lambda_e [P_a, P_b] = 0 \quad \rightarrow \quad \lambda_e \lambda_e = \lambda_{0_S}, \quad (\text{D.45})$$

$$[\tilde{P}_a, \tilde{J}_{bc}] = [\lambda_e P_a, \lambda_a J_{bc}] = \lambda_e \lambda_a [P_a, J_{bc}] \propto \lambda_e \delta_{ec}^{ab} P^e \quad \rightarrow \quad \lambda_e \lambda_a = \lambda_e, \quad (\text{D.46})$$

$$[\tilde{J}_{ab}, \tilde{J}_{cd}] = [\lambda_a J_{ab}, \lambda_a J_{cd}] = \lambda_a \lambda_a [J_{ab}, J_{cd}] \propto \lambda_a \delta_{ecd}^{abf} J_f^e \quad \rightarrow \quad \lambda_a \lambda_a = \lambda_a, \quad (\text{D.47})$$

$$[\tilde{P}_a, \tilde{Q}'] = [\lambda_e P_a, \lambda_d Q] = \lambda_e \lambda_d [P_a, Q] = 0 \quad \rightarrow \quad \lambda_e \lambda_d = \lambda_{0_S}, \quad (\text{D.48})$$

$$[\tilde{Z}_{ab}, \tilde{Q}'] = [\lambda_b J_{ab}, \lambda_d Q] = \lambda_b \lambda_d [J_{ab}, Q] = 0 \quad \rightarrow \quad \lambda_b \lambda_d = \lambda_{0_S}, \quad (\text{D.49})$$

$$[\tilde{P}_a, \tilde{Q}] = [\lambda_e P_a, \lambda_c Q] = \lambda_e \lambda_c [P_a, Q] \propto \lambda_d Q \quad \rightarrow \quad \lambda_e \lambda_c = \lambda_d, \quad (\text{D.50})$$

$$[\tilde{Z}_{ab}, \tilde{Q}] = [\lambda_b J_{ab}, \lambda_c Q] = \lambda_b \lambda_c [J_{ab}, Q] \propto \lambda_d Q \quad \rightarrow \quad \lambda_b \lambda_c = \lambda_d, \quad (\text{D.51})$$

$$[\tilde{J}_{ab}, \tilde{Z}_{cd}] = [\lambda_a J_{ab}, \lambda_b J_{cd}] = \lambda_a \lambda_b [J_{ab}, J_{cd}] \propto \lambda_b \delta_{ecd}^{abf} Z_f^e \quad \rightarrow \quad \lambda_a \lambda_b = \lambda_b, \quad (\text{D.52})$$

$$[\tilde{J}_{ab}, \tilde{Q}] = [\lambda_a J_{ab}, \lambda_c Q] = \lambda_a \lambda_c [J_{ab}, Q] \propto \lambda_c Q \quad \rightarrow \quad \lambda_a \lambda_c = \lambda_c, \quad (\text{D.53})$$

$$[\tilde{J}_{ab}, \tilde{Q}'] = [\lambda_a J_{ab}, \lambda_d Q] = \lambda_a \lambda_d [J_{ab}, Q] \propto \lambda_d Q \quad \rightarrow \quad \lambda_a \lambda_d = \lambda_d, \quad (\text{D.54})$$

$$[\tilde{Z}_{ab}, \tilde{Z}_{cd}] = [\lambda_b J_{ab}, \lambda_b J_{cd}] = \lambda_b \lambda_b [J_{ab}, J_{cd}] = 0 \quad \rightarrow \quad \lambda_b \lambda_b = \lambda_{0_S}, \quad (\text{D.55})$$

$$[\tilde{Z}_{ab}, \tilde{P}_c] = [\lambda_b J_{ab}, \lambda_e P_c] = \lambda_b \lambda_e [J_{ab}, P_c] = 0 \quad \rightarrow \quad \lambda_b \lambda_e = \lambda_{0_S}, \quad (\text{D.56})$$

$$\begin{aligned} \{\tilde{Q}, \tilde{Q}\} &= \{\lambda_c Q, \lambda_c Q\} = \lambda_c \lambda_c \{Q, Q\} \propto \lambda_e P_a + \lambda_b J_{ab} + \lambda_e Z_{abcde} \quad \rightarrow \quad (\text{D.57}) \\ &\rightarrow \lambda_c \lambda_c = \lambda_b, \quad \text{where we have set } \lambda_b = \lambda_e, \end{aligned}$$

and the other commutation relations give us results that agree with the above ones.

We observe that, in equation (D.57), we must set

$$\lambda_b = \lambda_e, \quad (\text{D.58})$$

in order to get consistent relations. For performing this identification with consistency, we have also exploited the statement which follows from Theorem 2.

This procedure fixes the degeneracy of the multiplication rules between the elements of

the subsets of \tilde{S} , and we are now able to write the following multiplication table

	λ_a	λ_b	λ_c	λ_d	λ_{0_S}	
λ_a	λ_a	λ_b	λ_c	λ_d	λ_{0_S}	(D.59)
λ_b	λ_b	λ_{0_S}	λ_d	λ_{0_S}	λ_{0_S}	
λ_c	λ_c	λ_d	λ_b	λ_{0_S}	λ_{0_S}	
λ_d	λ_d	λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	
λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	λ_{0_S}	

Then, after having performed the identification

$$a \leftrightarrow 0, \quad b \leftrightarrow 2, \quad c \leftrightarrow 1, \quad d \leftrightarrow 3, \quad 0_S \leftrightarrow 4, \quad (D.60)$$

we can finally rewrite the table above as follows (in the usual order):

	λ_0	λ_1	λ_2	λ_3	λ_4	
λ_0	λ_0	λ_1	λ_2	λ_3	λ_4	(D.61)
λ_1	λ_1	λ_2	λ_3	λ_4	λ_4	
λ_2	λ_2	λ_3	λ_4	λ_4	λ_4	
λ_3	λ_3	λ_4	λ_4	λ_4	λ_4	
λ_4	λ_4	λ_4	λ_4	λ_4	λ_4	

This is exactly the multiplication table of the semigroup $S_E^{(3)}$, which leads, as it was shown in Ref. [5]) through a S -expansion procedure (0_S -resonant-reduction), from the $osp(32/1)$ algebra to the hidden superalgebra underlying the eleven-dimensional supergravity theory, described in Ref.s [38, 39].

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